



Micro-controller X

Model: PXR4/5/7/9

Operation Manual

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| HIUCX | | 01 |

PXR4, PXR7

| PXF | 84, PXR7 | | 1 5 6 | 7 | 8 9 | 10 | 11 | 12 | 12 |
|----------|--|------------------|----------|--------|--------|----------|---------|----|----|
| | | PXR | | | 1 - [| Ι, | Ü | 14 | اً |
| Digit | Specification | Note | | | | | | | |
| 4 | <front dimensions=""></front> | | ↓ | | | | | | |
| | 48 X 48mm | | 4 | | | | | | |
| | 72 X 72mm | | 7 | | | | \perp | 4 | + |
| 5 | <input signal=""/> | | * | | | | | | |
| | Thermocouple °C Thermocouple °F | | l k | | | | | | |
| | Resistance bulb Pt100 3-wire type °C | | N | | | | | | |
| | Resistance bulb Pt100 3-wire type °F | | S | | | | | | |
| | 1 to 5V DC | | A | | | | | | |
| | 4 to 20mA DC | | В | _ | | _ | + | + | + |
| 6 | <control 1="" output=""></control> | | ¥ | | | | | | |
| | Relay contact output Voltage pulse output (24V DC) | | C | | | | | | |
| | 4 to 20mA DC output | Note 1 | Ĕ | | | | | | |
| 7 | <control 2="" output=""></control> | | | + | | 1 | \top | T | 十 |
| | None | | | Υ | | | | | |
| | Relay contact output | Note 2 | | Α | | | | | |
| | Voltage pulse output (24V DC) | Note 2 | | C E | | | | | |
| | 4 to 20mA DC output Re-transmission output (4 to 20mA DC) | Note 2 Note 2 | | R · | L | | | | |
| 8 | <revision code=""></revision> | Note 2 | | | 1 | + | + | + | + |
| 9 | <optional 1="" specifications=""></optional> | | | | | _ + | + | + | + |
| " | None | | | | 0 | | | | |
| | Alarm (1 pc.) | | | | 1 | | | | |
| | Alarm for heater break | Note 3 | | | 2 | : | | | |
| | Alarm (1 pc.) + Alarm for heater break | Note 3 | | | 3 | | | | |
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| | Alarm (1 pc.) + Ramp-soak Alarm for heater break + Ramp-soak | Note 3 | | | 5 6 | | | | |
| | Alarm (1 pc.) + Alarm for heater break + Ramp-soak | Note 3 | | | 7 | | | | |
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| | Alarm (2 pcs.) + Ramp-soak | | | | G | | | | |
| | Alarm (2 pcs.) + Alarm for heater break + Ramp-soak | Note 3 | | | Н | | | | |
| | Alarm (3 pcs.) Remote SV | Note 3 | | | N D | | | | |
| | Remote SV + Alarm (2 pcs.) | Note 3 | | | P | | | | |
| 10 | <pre><instruction manual=""> <power supply="" voltage=""></power></instruction></pre> | | | | | * | | T | 十 |
| | None 100 to 240V AC | | | | | N | | | |
| | English 100 to 240V AC | | | | | ۷ | | | |
| | None 24V DC English 24V DC | | | | | C B | | | |
| 44 | | | | | | | | ╁ | |
| 11 12 | <optional 2="" specifications=""> None</optional> | | | | | | 0 | 0 | 0 |
| 13 | RS485 (Modbus) communication | | | | | | М | - | ŏ |
| | RS485 (ASCII) communication | | | | | | N | 0 | 0 |
| | Digital input 1 point | l | | | | | S | 0 | 0 |
| | Digital input 2 points | Note 4 | | | | | T | 0 | 0 |
| | RS485 (Modbus) communication + Digital input 1 point RS485 (ASCII) communication + Digital input 1 point | | | | | | V W | 0 | 0 |
| | No+00 (AOCH) COMMUNICATION + Digital input 1 point | | | | | | VV | U | |

Note 1: Cannot be combined with heater break alarm.

(2, 3, 6, 7, H cannot be specified on 9th digit.)

Note 2: In case of the combination 9th digit code: 3, 7, F, G, H, M or P and PXR4 the following installation condition are required.

Note 3: Cannot be combined with RS485 + 1-point digital input.

(V and W cannot be specified on 11th digit.)

Note 4: In the case of control output 2, either of heater break alarm or remote SV input can be selected. (A, C, E and R on the 7th digit, and 2,3,6,7,H, D and P on the 9th digit cannot be specified.)

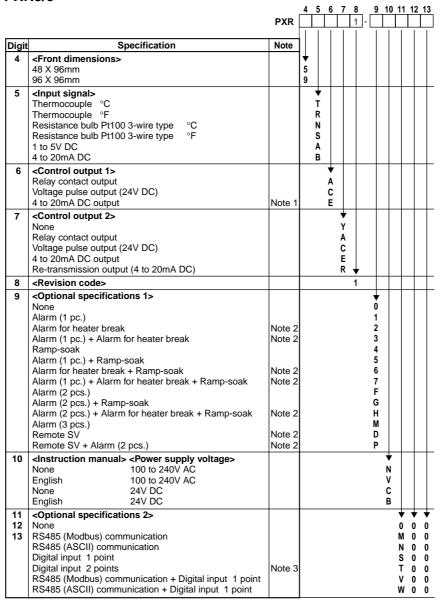
Input signal, measurement range, and set value at the time of deliver are as follows.

When thermocouple is specified: Thermocouple K, Measurement range; 0 to 400°C, Set value; 0°C When resistance bulb is specified: Pt, Measurement range; 0 to 150°C, Set value; 0°C When voltage/current is specified: Scaling; 0 to 100%, Set value; 0%

For the cases other than the above, specify input signal and measurement range. Input signal of the thermocouple and the resistance bulb can be switched by key operation on the front panel.

The actuating method of the control output has been set to reverse for control output 1, and to direct for control output 2 at the time of delivery. Note that reverse and direct actuation can be switched by key operation on the front panel.

PXR5/9



Note 1: Cannot be combined with heater break alarm.

(2, 3, 6, 7, H cannot be specified on 9th digit.)

Note 2: Cannot be combined with RS485 + 1-point digital input.

(V and W cannot be specified on 11th digit.)

Note 3: In the case of control output 2, either of heater break alarm or remote SV input can be selected.

(A, C, E and R on the 7th digit, and 2,3,6,7,H, D and P on the 9th digit cannot be specified.)

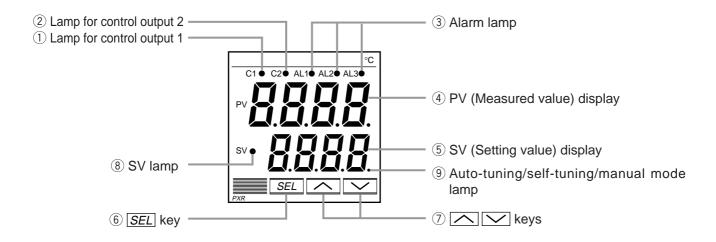
Input signal, measurement range, and set value at the time of deliver are as follows. When thermocouple is specified: Thermocouple K, Measurement range; 0 to 400°C, Set value; 0°C When resistance bulb is specified: Pt, Measurement range; 0 to 150°C, Set value; 0°C When voltage/current is specified: Scaling; 0 to 100%, Set value; 0%

For the cases other than the above, specify input signal and measurement range. Input signal of the thermocouple and the resistance bulb can be switched by key operation on the front panel.

The actuating method of the control output has been set to reverse for control output 1, and to direct for control output 2 at the time of delivery. Note that reverse and direct actuation can be switched by key operation on the front panel.

1 Part Names and Functions

This chapter explains the part names and functions on the face panel. The face panel has the PV and SV displays, the status indicating lamp, and the setting keys, etc. Those functions are explained below. Please read and understand them before using the PXR. For details about the setting of parameters, see Chapter 2.



- 1 Lamp for control output 1 Lights up while control output 1 stays ON.
- ② Lamp for control output 2 Lights up while control output 2 stays ON.
- 3 Alarm lamp

Lights up on detecting an alarm. The alarm output is turned ON at the same time.

If the optional heater break alarm is provided, the AL3 lamp lights up on detecting a heater break.

④ PV (Measured value) display Displays the PV. When setting a parameter, its name appears.

- ⑤ SV (Setting value) display
 Displays the SV. When setting a parameter, its value appears.
- 6 SEL key

Used to select a parameter block and a parameter, and register a set value.

- (7) keys
 Used to change the SV, call parameters, and change parameter values.
- (8) SV lamp Lights up while the SV is displayed in the SV display. When parameters and data are displayed, the SV lamp goes out.
- (9) Auto-tuning/self-tuning/manual mode lamp Flashes under an auto-tuning or self-tuning operation. The lamp is kept on in manual mode.

2 Operations

This chapter explains how to set the SV (Setting value) and the parameters for the PXR.

2-1 Parameter list

Parameters for the PXR are classified into operation parameters, and the first block, the second block and the third block parameters according to the frequency of use. The second and the third block parameters are used at initialization or when they are absolutely necessary.

Operation parameter

| Parameter display symbol | Parameter name | Description | Setting range and factory default setting (*) | Parameter mask DSP | Reference page |
|--------------------------|--------------------------------|--|---|-----------------------|--|
| (PV) | | Displays the currently measured temperature (Measurement value). | Setting not allowed. | dP13-64 | See page 78 for the method of turning on/off PV. |
| (SV) | Set temperature (Set value) | Displays the set temperature (Set value). | | Mask not allowed. | 14 |

Parameters of the first block

| Parameter display symbol | Parameter name | Description | n | Setting range and factory default setting (*) | User's set value | Parameter mask DSP | Reference page |
|--------------------------|------------------------------|--|---|---|---------------------|-----------------------|----------------|
| ПЯлЦ | Manual mode selection | Switches between Auto a modes. | nd Manual operation | oN: Manual mode oFF: Auto mode* | | dP13-32 | 15 |
| 5/64 | Standby setting | Switches between RUN a control. | and Standby for | oN: Control standby (Output: OFF, Alarm: OFF) oFF: Control RUN* | | dSP1-1 | 16 |
| [Nod | Remote/local setting | Switches between remote | and local operations. | rEM: Remote LoCL: Local | | dp13-8 | 17 |
| ProS | Ramp-soak control | | | oFF: Stop* rUn: Start HLd: Hold | | dSP1-2 | 18 |
| LREH | Alarm latch cancel | Cancels the alarm latch. | | 0: Keeps the alarm latch.* 1: Opens up the alarm latch. | | dSP1-4 | 19 |
| ЯГ | Auto-tuning | Used for setting the const by auto-tuning. | tants for P, ζ , and d | 0: OFF (Resets the auto-tuning or does not use it.)* 1: ON (Performs the auto-tuning in the SV standard type.) 2: ON (Performs the auto-tuning in low PV type (SV value-10%FS).) | | dSP1-8 | 20 |
| ΓΠ- Ι | Timer 1 display | Displays the remaining ti | me of timer 1. | - (Unit: seconds) | | dSP1-16 | 21 |
| <u> </u> | Timer 2 display | Displays the remaining ti | me of timer 2. | - (Unit: seconds) | | dSP1-32 | 21 |
| ГП-3 | Timer 3 display | Displays the remaining ti | | - (Unit: seconds) | | dSP1-64 | 21 |
| RL I | Set value of alarm 1 | Sets the value at which alarm 1 is detected. | When alarm type 1 is 0 to 15, or 32 to | When the alarm type is absolute value: 0 to 100%FS (*:10) | | dSP1-128 | 22* |
| RI-L | Lower limit value of alarm 1 | Sets the lower limit value at which alarm 1 is detected. | 34, and \$\beta\$ \ \cdot - \mathcal{H}\$ or \$\beta\$ \ \beta\$ - \mathcal{H}\$ or \$\beta\$ \ \beta\$ - \mathcal{L}\$ is displayed | When the alarm type is deviation: -100 to 100%FS (*:10) | | dSP2-1 | 22* |
| R 1-H | Upper limit value of alarm 1 | Sets the upper limit value at which alarm 1 is detected. | when alarm type 1 is 16 to 31. | ` , | | dSP2-2 | 22* |
| RL2 | Set value of alarm 2 | Sets the value during which alarm 2 is detected. | RL 2 is displayed when alarm type 2 is 0 | When the alarm type is absolute value: 0 to 100%FS (*:10) | | dSP2-4 | 22* |
| R2-L | Lower limit value of alarm 2 | Sets the lower limit value at which alarm 2 is detected. | to 15 or 32 to 34, and R2-H or R2-1 is displayed when alarm | When the alarm type is deviation: | | dSP2-8 | 22* |
| R2-X | Upper limit value of alarm 2 | Sets the upper limit value at which alarm 2 is detected. | displayed when alarm type 2 is 16 to 31. | -100 to 100%FS (*:10) | | dSP2-16 | 22* |
| RL3 | Set value of alarm 3 | Sets the value at which alarm 3 is detected. | RL 3 is displayed when alarm type 3 is 0 | When the alarm type is absolute value: 0 to 100%FS (*:10) | | dSP2-32 | 22* |
| R3-L | Lower limit value of alarm 3 | Sets the lower limit value at which alarm 3 is detected. | to 15 or 32 to 34, and 33-H or 33-L is | When the alarm type is deviation: | | dSP2-64 | 22* |
| R3-H | Upper limit value of alarm 3 | Sets the upper limit value at which alarm 3 is detected. | displayed when alarm type 3 is 16 to 31. | -100 to 100%FS (*:10) | | dSP2-128 | 22* |
| LoE | | Specifies whether or not to a parameters. | | O: All settings are changeable both from the face panel and via communication.* 1: All settings are unchangeable from the face panel, but changeable via communication. 2: Only the SV is changeable from the face panel, and all settings are changeable via communication. 3: All settings are changeable from the face panel, but unchangeable via communication. 4: All settings are unchangeable from the face panel or via communication. 5: Only the SV is changeable from the face panel, but all settings are unchangeable via communication. | | dSP3-1 | 23 |

Note: The parameters for which * is marked with the page number in Reference page are related to Remedies of "4" on page 79.

Parameters of the second block

Note: The parameters for which * is marked with the page number in Reference page are related to Remedies of "4" on page 79.

| Parameter display symbol | Parameter name | Description | Setting range and factory default setting (*) | User's set value | Parameter mask DSP | Reference page |
|--------------------------|---|---|---|------------------|-----------------------|----------------|
| Р | Proportional band | Set P to 0.0 to select the ON/OFF control (Two-position control). | 0.0 to 999.9% (*: 5.0) | | dSP3-2 | 24 |
| Ĺ | Integral time | | 0 to 3200 seconds (*: 240) | | dSP3-4 | 25 |
| d | Derivative time | | 0.0 to 999.9 seconds (*: 60.0) | | dSP3-8 | 26 |
| XY5 | Hysteresis range for ON/OFF control | Sets the hysteresis for ON/OFF control. | 0 to 50%FS (*: equivalent of 1.0°C) | | dSP3-16 | 27* |
| Cool | Cooling-side proportional band coefficient | | 0.0 to 100.0 (*: 1.0) | | dSP3-32 | 28 |
| db | Cooling-side proportional band shift | | -50.0 to +50.0 (*: 0.0) | | dSP3-64 | 29 |
| ЬЯL | Output convergence value | | -100 to 100% (*: single 0.0, dual 50.0) | | dSP3-128 | 30 |
| Rr | Anti-reset windup | | 0 to 100%FS (*: 100%FS) | | dSP4-1 | 30 * |
| [[rL | Control algorithm | Selects the control algorithm. | PID: Runs normal PID control.* FUZY: Runs PID control with fuzzy logic. SELF: Runs PID control with self-running. | | dSP4-2 | 31 |
| SLFb | PV (Measured value) stable range | Sets the PV stable range for the self-tuning operation. | 0 to 100%FS (*: 2%FS) | | dSP4-4 | 35 * |
| onoF | Setting HYS (Hysteresis) mode | Selects the hysteresis operation at ON/OFF control. | oFF: Starts the two-position control at the values of SV+HYS/2 and SV-HYS/2. on: Starts the two-position control at the values of SV and SV+HYS, or SV and SV-HYS.* | | dSP4-8 | 36 |
| ۲٤ | Cycle time of control output 1 | Not shown at 4-20mA DC output | RLY, SSR: 1 to 150 seconds (*: Contact output = 30, SSR/SSC-driven output = 2) | | dSP4-16 | 37 |
| re2 | Cycle time of control output 2 (cooling-side) | | 1 to 150 seconds (*: 30) | | dSP4-32 | 38 |
| P-n2 | Input signal code | Set this parameter when changing the types of temperature sensors. | 1 to 16 (*: specified by customer while ordering) Note 1 | | dSP4-64 | 39 |
| P-5L | Lower limit of measuring range | | -1999 to 9999 (*: specified by customer while ordering) Note 1 | | dSP4-128 | 40 |
| P-5U | Upper limit of measuring range | | -1999 to 9999 (*: specified by customer while ordering) Note 1 | | dSP5-1 | 40 |
| P-dP | Setting the decimal point position | | 0 to 2 (*: specified by customer while ordering) Note 1 | | dSP5-2 | 42 |
| p-F | °C / °F selection | | °C / °F | | dSP5-4 | 40 |
| PUOF | PV (Measured value) offset | | -10 to 10%FS (*: 0) | | dSP5-8 | 43 |
| SUOF | SV (Setting value) offset | | -50 to 50%FS (*: 0) | | dSP5-16 | 44* |
| P-dF | Time constant of input filter | | 0.0 to 900.0 seconds (*: 5.0) | | dSP5-32 | 45* |
| ALN I | Alarm type 1 | Sets the types of alarm operations. | 0 to 34 (*: 0/5) | | dSP5-64 | 46 |
| RLN2 | Alarm type 2 | Sets the types of alarm operations. | 0 to 34 (*: 0/9) | | dSP5-128 | 46 |
| ALN3 | Alarm type 3 | Sets the types of alarm operations. | 0 to 34 (*: 0) | | dSP6-1 | 46 |
| 5/R/ | Status display of ramp-soak | | - (*: OFF) | | dSP6-2 | 50 |
| Pro | Selecting ramp- soak execute type | Selects ramp-soak patterns. | 1: Performs 1st to 4th segments.* 2: Performs 5th to 8th segments. 3: Performs 1st to 8th segments. | | dSP6-4 | 49 |
| 5ū-1 | 1st target value /Switching-SV value | Sets the 1st target SV of ramp-soak operation. / Selected at switching- SV function for DI1 | Within the SV limit. (*: 0%FS) | | dSP6-8 | 50 * |
| ΓΠ Ir | First ramp segment time | Sets the first ramp segment time. | 0 to 99h59m (*: 0.00) | | dSP6-16 | 50 |

Note: The parameters for which * is marked with the page number in Reference page are related to Remedies of "4" on page 79.

| Parameter | Parameter name | Description | Setting range and factory default setting (*) | User's | | Reference |
|---|--------------------------|---|---|-----------|---------------------|-----------------|
| display symbol | 1st soak segment | Sets the 1st soak segment time. | 0 to 99h59m (*: 0.00) | set value | mask DSP dSP6-32 | page |
| ΓΠ 15 ———————————————————————————————————— | time | | , | | | 50 |
| 50-2 | 2nd target SV | Sets the 2nd target SV of ramp-soak operation. | Within the SV limit. (*: 0%FS) | | dSP6-64 | 50 [*] |
| ΓΠ2r | 2nd ramp segment time | Sets the 2nd ramp segment time. | 0 to 99h59m (*: 0.00) | | dSP6-128 | 50 |
| FN25 | 2nd soak segment time | Sets the 2nd soak segment time. | 0 to 99h59m (*: 0.00) | | dSP7-1 | 50 |
| 50-3 | 3rd target SV | Sets the 3rd target SV of ramp-soak operation. | Within the SV limit. (*: 0%FS) | | dSP7-2 | 50 [*] |
| ГПЗг | 3rd ramp segment time | Sets the 3rd ramp segment time. | 0 to 99h59m (*: 0.00) | | dSP7-4 | 50 |
| гл35 | 3rd soak segment time | Sets the 3rd soak segment time. | 0 to 99h59m (*: 0.00) | | dSP7-8 | 50 |
| 55-4 | 4th target SV | Sets the 4th target SV of ramp-soak operation. | Within the SV limit. (*: 0%FS) | | dSP7-16 | 50 [*] |
| ГПЧг | 4th ramp segment time | Sets the 4th ramp segment time. | 0 to 99h59m (*: 0.00) | | dSP7-32 | 50 |
| глч5 | 4th soak segment time | Sets the 4th soak segment time. | 0 to 99h59m (*: 0.00) | | dSP7-64 | 50 |
| 50-5 | 5th target SV | Sets the 5th target SV of ramp-soak operation. | Within the SV limit. (*: 0%FS) | | dSP7-128 | 50 [*] |
| ΓΠ5r | 5th ramp segment time | Sets the 5th ramp segment time. | 0 to 99h59m (*: 0.00) | | dSP8-1 | 50 |
| глѕѕ | 5th soak segment time | Sets the 5th soak segment time. | 0 to 99h59m (*: 0.00) | | dSP8-2 | 50 |
| 5ũ-6 | 6th target SV | Sets the 6th target SV of ramp-soak operation. | Within the SV limit. (*: 0%FS) | | dSP8-4 | 50 [*] |
| ГПБг | 6th ramp segment time | Sets the 6th ramp segment time. | 0 to 99h59m (*: 0.00) | | dSP8-8 | 50 |
| гльѕ | 6th soak segment time | Sets the 6th soak segment time. | 0 to 99h59m (*: 0.00) | | dSP8-16 | 50 |
| 55-7 | 7th target SV | Sets the 7th target SV of ramp-soak operation. | Within the SV limit. (*: 0%FS) | | dSP8-32 | 50 [*] |
| רחחר | 7th ramp segment time | Sets the 7th ramp segment time. | 0 to 99h59m (*: 0.00) | | dSP8-64 | 50 |
| <i>rnn</i> 5 | 7th soak segment time | Sets the 7th soak segment time. | 0 to 99h59m (*: 0.00) | | dSP8-128 | 50 |
| 55-8 | 8th target SV | Sets the 8th target SV of ramp-soak operation. | Within the SV limit. (*: 0%FS) | | dSP9-1 | 50 [*] |
| ГЛ8- | 8th ramp segment time | Sets the 8th ramp segment time. | 0 to 99h59m (*: 0.00) | | dSP9-2 | 50 |
| rn85 | 8th soak segment time | Sets the 8th soak segment time. | 0 to 99h59m (*: 0.00) | | dSP9-4 | 50 |
| Nod | Ramp-soak mode | Selects the power-on start, repeat, and standby functions for ramp-soak operations. | 0 to 15 (*: 0) | | dSP9-8 | 50 |

Note 1: When a customer does not specify the settings while ordering, the following settings are selected as factory defaults.

Thermocouple input: Thermocouple K Measured range: 0 to 400°C Resistance bulb input: Measured range: 0 to 150°C

Voltage/Current input: Scaling: 0 to 100%

Parameters of the third block

Note: The parameters for which * is marked with the page number in Reference page are related to Remedies of "4" on page 79

| Parameter | Parameter name | Description | Setting range and factory | User's | Parameter | |
|----------------|--|---|---|-----------|-----------|-----------------|
| display symbol | | , | default setting (*) | set value | mask DSP | page |
| P-n! | Control action | Specifies control action and output at the input burn-out. | 0 to 19 (*: specified by customer while ordering) Note 2 | | dSP9-16 | 53 |
| 5ū-L | SV (Setting value) lower limiter | Sets the lower limit of the SV. | 0 to 100%FS (*: 0%FS) | | dSP9-32 | 54* |
| 5ū-X | SV (Setting value) upper limiter | Sets the upper limit of the SV. | 0 to 100%FS (*: 100%FS) | | dSP9-64 | 54* |
| 9F A 1 | Delay time 1 | Delay time or timer value for alarm 1 relay. | 0 to 9999 seconds (*: 0) | | dSP9-128 | 55 |
| 9F 75 | Delay time 2 | Delay time or timer value for alarm 2 relay. | 0 to 9999 seconds (*: 0) | | dP10-1 | 55 |
| 4F 73 | Delay time 3 | Delay time or timer value for alarm 3 relay. | 0 to 9999 seconds (*: 0) | | dP10-2 | 55 |
| [[| Current transe display | Displays the current detector input value for HB alarm. | - | | dP10-4 | 57 |
| НЬ | HB (Set value of heater break alarm) setting | Sets the operation value that detects the heater break. | 0 to 50.0A (Setting to 0.0A turns off the HB alarm.) (*: 0.0) | | dP10-8 | 57 |
| R (hy | Alarm 1 hysteresis | Sets the hysteresis range of ON and OFF of alarm 1. | 0 to 50%FS (*: 1) | | dP10-16 | 59 [*] |
| A5ra | Alarm 2 hysteresis | Sets the hysteresis range of ON and OFF of alarm 2. | 0 to 50%FS (*: 1) | | dP10-32 | 59 [*] |
| ЯЗҺУ | Alarm 3 hysteresis | Sets the hysteresis range of ON and OFF of alarm 3. | 0 to 50%FS (*: 1) | | dP10-64 | 59 * |
| R loP | Alarm 1 options | Sets the optional functions of alarms 1, 2 and 3. | 000 to 111 (*: 000) | | dP10-128 | 60 |
| RZoP | Alarm 2 options | Alarm latch (1: use, 0: not use) | 000 to 111 (*: 000) | | dP11-1 | 60 |
| R3oP | Alarm 3 options | ☐ Alarm of error status (1: use, 0: not use)☐ De-energized output (1: use, 0: not use)☐ | 000 to 111 (*: 000) | | dP11-2 | 60 |
| PLE I | Lower limit for output 1 | Sets the lower limit for output 1. | -3.0 to 103.0% (*: -3.0) | | dP11-4 | 62 |
| PHE I | Upper limit for output 1 | Sets the upper limit for output 1. | -3.0 to 103.0% (*: 103.0) | | dP11-8 | 62 |
| PLE2 | Lower limit for output 2 | Sets the lower limit for output 2. | -3.0 to 103.0% (*: -3.0) | | dP11-16 | 62 |
| PHE2 | Upper limit for output 2 | Sets the upper limit for output 2. | -3.0 to 103.0% (*: 103.0) | | dP11-32 | 62 |
| РСИГ | Output limit types | Sets the limit types of outputs 1 and 2 (breaking the limit, or maintained within the limit). | 0 to 15 (*: 0) | | dP11-64 | 63 |
| ا کلاه | Output value (MV) display | Displays the value of output 1. | - | | dP11-128 | 64 |
| 2 کالاه | Output value (MV) display | Displays the value of output 2. | - | | dP12-1 | 64 |
| r[d | RCJ (Cold junction compensation) setting | Sets the cold junction compensation function to ON/OFF. | ON: Performs the RCJ (Cold junction compensation).* OFF: Does not perform the RCJ (Cold junction compensation). | | dP12-2 | 65 |
| GRIN | PV gradient | | 0.001 to 2.000 (*: 1.000) | | dP12-4 | |
| RdJD | User-definable zero adjustment | Shifts the zero point of input value. | -50 to 50%FS (*: 0) | | dP12-8 | 66 [*] |
| RdJS | User-definable span adjustment | Shifts the span of input value. | -50 to 50%FS (*: 0) | | dP12-16 | 66* |
| dī-l | DI1 (Digital input 1) operation | Sets the DI1 operations. | 0 to 12 (*: 0=OFF) | | dP12-32 | 67 |
| q <u>r</u> -5 | DI2 (Digital input 2) operation | Sets the DI2 operations. | 0 to 12 (*: 0=OFF) | | dP12-64 | 67 |
| 55no | Station No. | Sets the station No. for communication. | 0 to 255 (Setting to \$\mathbb{U}\$ does not start the communications function.) (*: 1) | | dP12-128 | 70 |
| ΕοΠ | Parity setting | Sets the parity for communication. (The baud rate is fixed at 9600bps. | 0: Odd parity* 1: Even parity 2: No parity | | dP13-1 | 71 |

Note 2: The following settings are selected as factory defaults depending on the model you order.

Seventh digit = Y model: 0

Seventh digit = A model: 4

Note: The parameters for which * is marked with the page number in Reference page are related to Remedies of "4" on page 79.

| | | T | 1.0 | 1 0 | |
|---------------------------------|--|---|---|-----------------------|----|
| Parameter display symbol | Parameter name | Description | Setting range and factory default setting (*) | Parameter mask DSP | |
| PEaL | Communication protocol setting | Switches communication protocols between Modbus and ASCII | 0 : Z-ASCII 1 : Modbus (RTU) | dP13-2 | 72 |
| Ro-F | Re-transmission output type setting | Sets the type of signals to be outputted from re-transmission output. | Setting range 0 : PV / 1 : SV / 2 : MV/ 3 : DV (* : 0) | dP13-4 | 73 |
| Ro-L | Re-transmission output scaling base side setting | Re-transmission output scaling setting on the base side | Setting range -100.0 to 100.0% (*: 0.0) | dP13-4 | 74 |
| Ro-H | Re-transmission output scaling span side setting | Re-transmission output scaling on the span side | Setting range -100.0 to 100.0% (*: 100.0) | dP13-4 | 74 |
| rENO | Remote SV input zero adjustment | Shifts the zero point of input value. | -50 to 50%FS (*: 0) | dP13-16 | 75 |
| r EMS | Remote SV input span adjustment | Shifts the span point of input value. | -50 to 50%FS (*: 0) | dP13-16 | 75 |
| r-dF | Remote SV input filter constant | Sets the filter constant of remote SV input value. | 0.0 to 900.0 seconds (*: 0.0) | dP13-16 | 76 |
| r Sü | Remote SV input value display | Displays remote SV input value. | - | dP13-16 | 77 |
| dSP 1 dSP9 dP 10 dP 13 | Parameter mask | Sets whether or not to display each parameter. | 0 to 255 (*: specified by customer while ordering) | _ | 78 |

2-2 Basic operations

Just after power-on:

The display below appears just after power-on.



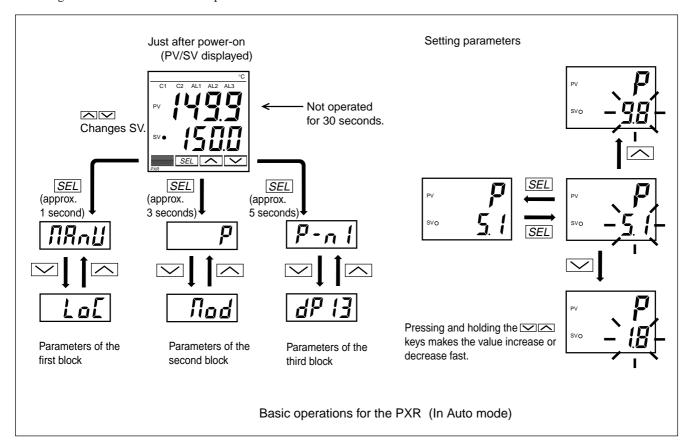
Status at delivery
< Auto mode >

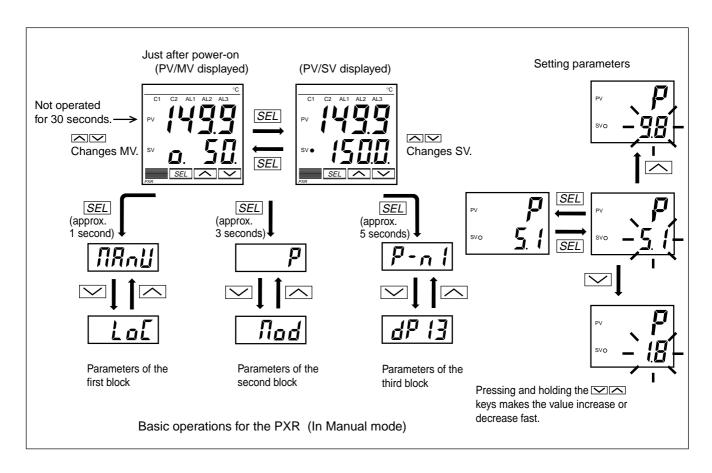


<In Manual mode>

How to switch parameters:

The figure below shows the basic operations for the PXR.





How to set values:

key: One press increases the value by 1.

Press and hold this key to increase the value fast.

key: One press decreases the value by 1.

Press and hold this key to decrease the value fast.

How to register the set data:

By pressing the **SEL** key, the displayed values are registered.

Note that the SV (SV0) will be registered in 3 seconds without any operation.

2-3 Parameter functions and method of settings

Method of setting the SV (Setting value)

[Description] ——

- The SV is a target value for control.
- Any SV that is outside of the range set in the parameters of $5\vec{u} L$ (lower limit) and $5\vec{u} H$ (upper limit) of the third block cannot be set. (See page 54.)

Related parameters: 5<u>u</u>-L (page 54)

5.. - **H** (page 54)

[Setting example] Changing the SV from 250°C to 1195°C -

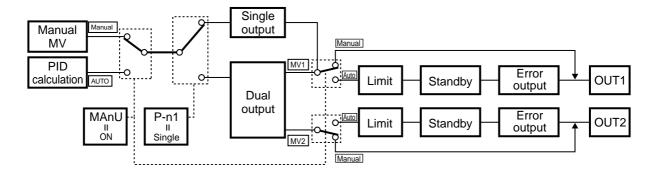
| Display | Operating procedure |
|----------------|---|
| 749 •• 250 | 1. Press the or keys to display ; 195. |
| 249 •• 1195 | 2.1195 will be registered in the SV (SV0) in three seconds. After that, the controller will operate with the SV being 1195. |

Manual mode setting (Settings: oFF/on)

[Description] -

- This parameter switches the control mode between Auto and Manual.
- During Manual operation, the decimal point is kept on at the far right in the SV display section.
- During Manual operation, auto tuning or self tuning is not done. If the mode is switched to Manual while auto or self tuning is being done, the tuning is forcibly terminated. The PID parameter remains the same in such
- Manual operation output is not limited by MV limit.
- · Manual operation can be carried out during standby operation.
- The operation output set value during Auto/Manual operation mode and manual mode is stored in non-volatile memory. It is kept stored even if a power interruption occurs. When the power is turned on again, the state before the power interruption is resumed.
- The following table lists the operation output at the time of switching between Auto and Manual..

| $Auto \to Manual$ | $Manual \to Auto$ |
|---------------------------|--------------------------|
| Balanceless bumpless | MV output according to |
| (Switches to manual mode, | PID operation |
| holding the MV value just | (Sudden change may occur |
| before the switching.) | to the MV value.) |



[Setting example] Switching to manual mode

| L | ample] Ownering to mandar mode |
|-----------------------------|---|
| Display | Operating procedure |
| 1499 1500 | 1. Press and hold the SEL key for one second, and TRnU is displayed. |
| ∏R∩U oFF | |
| ПĄ~U - <u>ъ£</u> £- | 2. Press the \overline{SEL} key once, and the current set value (${}_{\alpha}FF$) on the SV display section starts flickering. |
| ПЯ _О Ц -è-́с- | 3. Press the or the keys to display an. |
| NANU on | 4. Press the <u>SEL</u> key once, and the manual lamp at the lower right corner comes on, indicating that the mode has been switched to Manual. |
| 1499 1500 | 5. To display operation status, press and hold the SEL key for two seconds. |

5万占当 Standby setting (Settings: oFF/on)

[Description] -

- This parameter switches the control between RUN and Standby.
- During standby, the control output and the alarm output stay OFF, like the standby for ramp-soak operation.
- While the alarm with a hold is selected, the hold function takes effect after changing the Standby setting from ON to OFF.
- 5764 is displayed during the standby for ramp-soak operations or the controller changes to the standby state in case of the occurrence of errors.
- The other operations are the same as those of the rampsoak standby.
- The setting of ON/OFF for standby is saved after poweroff.

- When the standby is set to ON during the auto-tuning, self-tuning, and ramp-soak operations, those operations will stop. (The PID constant will not be renewed.) Even through it is set to OFF later, the auto-tuning, self-tuning, and ramp-soak operations will not be re-started.
- During standby, the ON-delay timer is reset. When returning to RUN from the standby state, the timer will start from the beginning.

[Setting example] Starting the control-

| Display | Operating procedure |
|-----------------------------|--|
| 1499 1500 5764 6FF | 1. Press and hold the SEL key for one second. TRail will be displayed. Then press the key once. |
| 57,69 - ₉ 5,5 | 2. Press the SEL key once. The current setting (off) flashes on the SV display. |
| 21.PA | 3. Press the or keys to display on. |
| 57.64 en | 4. Press the SEL key once. The standby state for control is selected. (control output and all the alarm outputs: OFF) |
| - <u>isōo</u> - | 5. If you want to display the operation status, press and hold the SEL key for two seconds. The value on the SV display will flash, indicating the standby status. |



Local/remote operation setting (Setting range: LoCL/rEM) (Option)

[Description] -

· This parameter is used to switch between local and remote operations.

| Set value | Operation |
|-----------|--|
| LoEL | Performs local operation. |
| rEN | Performs remote operation. |
| | (", 5;" and the set value (SV) are displayed |
| | alternately in the SV display section on the |
| | front face while in remote operation.) |

* Local operation: Control by SV set by the keys on the

> front face, ramp-soak operation, SV selection determined by digital input, and SV setting via communication

* Remote operation: Control by SV determined by Remote

SV input

Related parameters: rEMI (page 75)

r **E** [75] (page 75)

r-dF (page 76)

r 5 u (page 77)

[Setting example] Switching to remote operation -

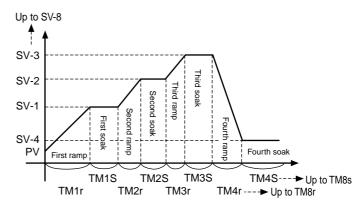
| Display | Operating procedure |
|-----------------------------|--|
| 1499 1500 5764 6FF | 1. Press and hold the SEL key for one second. 5. Ly will be displayed on the PV display section. |
| [Nob Lo[L | 2. Press the keys to display [nod. |
| -LοCL | 3. Press the \boxed{SEL} key once. The current setting ($L_{\Omega} \subseteq L$) in the SV display section flickers. |
| <u> 7 Ē</u> [[| 4. Press the keys to display , E |
| ENOB | 5. Press the SEL key once. Flickering stops and the operation is switched to remote. |
| 14 <u>99</u> 1500 | 6. To display the operation status, press and hold the SEL key for two seconds. |

ProL

Ramp-soak control (Settings: oFF/rUn/hLd) (Option)

[Description] -

- This function automatically changes the SV (Setting value) according to the program pattern set in advance as shown in the right line graph. Up to eight pairs of rampsoak operation can be programmed.
- The first ramp starts at the PV (Measured value) that is the one just before running the program.
- The program can also automatically run at power-on (Power-on starting function). Refer to the parameter of Π_{ad} (page 47).



Ramp: the section in which the SV changes toward the target value. Soak: the section in which the SV is the target value, and remains unchanged.

Related parameters: $5\Gamma R\Gamma$ (page 50) $5\mu - 1$ to $5\mu - 1$ (page 50)

Pro (page 49)

[Setting example] Starting the ramp-soak operation

| Display | Operating procedure |
|-----------------------------|--|
| 1499 1500 5F64 6FF | 1. Press and hold the SEL key for one second. 5. by will be displayed on the PV display. |
| Pro[off | 2. Press the key to display ProL |
| Pro[-pFF- | 3. Press the \overline{SEL} key once. The current setting ($_{\alpha}FF$) flashes on the SV display. |
| Pr. q.L. | 4. Press the or keys to display run. |
| Pro5 rUn | 5. Press the <u>SEL</u> key once. Then, the program will start according to the ramp-soak pattern that is set in advance. |
| 1499 1500 | 6. If you want to display the operation status, press and hold the SEL key for two seconds. |

LACH

Canceling the alarm latch (Setting range: 0/1) (Option)

[Description] -

• This parameter cancels the alarm latch when it is latching.

Related parameters:

R lo**P** to **R3oP** (page 60)

[Setting example] Opening up the alarm latch -

| Display | Operating procedure |
|-----------------------------|---|
| 1499 1500 5764 6FF | 1. Press and hold the SEL key for one second. 51.64 will be displayed on the PV display. |
| LACH | 2. Press the key to display LREH. |
| [| 3. Press the SEL key once. The current setting ([]) flashes on the SV display. |
| L | 4. Press the or keys to display \(\extstyle \). |
| LACH | 5. Press the SEL key once. I will stop flashing and will change to I in a few seconds. |
| 1499 1500 | 6. If you want to display the operation status, press and hold the SEL key for two seconds. |

RI

Auto-tuning function (Settings: 0/1/2)

[Description] -

[Note]

If the controller is powered off during auto-tuning, this makes the auto-tuning ineffective with each parameter of P, \bar{L} , and d unchanged. To start the auto-tuning operation, set $R\Gamma$ to "1" or "2" again.

- To suspend the auto-tuning, set $R\Gamma$ to "0". This makes the auto-tuning cancel with each parameter of P, Γ , and Γ unchanged.
- Once the parameters of P, ζ , and d are set automatically by the auto-tuning, those parameters are stored in the controller even after it is powered off. Therefore, it is not necessary to execute the auto-tuning again.
- By setting **R!** to "1" or "2", the auto-tuning operation starts, and at the end of the tuning, **!!** will be displayed automatically to **R!**.
- After the auto-tuning operation, the controller starts to operate at the automatically set values of P, L, and d.
- A decimal point at the right end of the SV display flashes during auto-tuning.

• There are two codes for AT:

Setting code [1]: SV standard type

Performs the auto-tuning based on the SV.

Setting code [2]: Low PV type

Performs the auto-tuning based on the

SV-10%FS.

[Note]

Since ON/OFF control is performed during auto-tuning, overshoot against the SV may occur. To reduce the overshoot, execute the auto-tuning operation with the setting code [2] (Low PV) selected.

• The auto-tuning can be executed both just after power-on and in a control or stable status.

Related parameters:

p (page 24)

[(page 25)

d (page 26)

Ar (page 30)

[ooL (page 28)

[Setting example] Setting the auto-tuning operation to 1 —

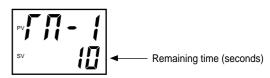
| Display | Operating procedure |
|-----------------------------|---|
| 1499 1500 5F64 oFF | 1. Press and hold the SEL key for one second. 5. by will be displayed on the PV display. |
| R [| 2. Press the ✓ key to display # |
| -, Q}- | 3. Press the SEL key once. The current setting (1) flashes on the SV display. |
| P.F. | 4. Press the or keys to display \(\eta \). |
| Rr Nr | 5. Press the SEL key once. I will stop flashing and the auto-tuning will start. During auto-tuning, a decimal point at the right end of the SV display flashes. |
| RT 0 | 6. When the auto-tuning finishes properly, a decimal point stops flashing, and the set values of <i>P</i> , \bar{L} , and <i>d</i> parameters change. When the auto-tuning finishes abnormally, a decimal point stops flashing, but the set values of <i>P</i> , \bar{L} , and <i>d</i> parameters remain unchanged. |
| 1499 1500 | 7. If you want to display the operation status, press and hold the SEL key for two seconds. |

FR-1, **FR-2**, **Displaying ON-delay alarm or the remaining time of timers** (unit: seconds) (Option)

[Description] -

- These parameters display the remaining time of Timers 1, 2 and 3.
- The remaining time of the ON/OFF-delay timer is counted down. When the counter shows [], the alarm relay is closed.
- During count-down, if the PV changes to the value of the temperature at which the alarm is set to OFF, or if "DI" for the timer is set to OFF, the counter is reset, and the alarm relay is opened.

• / // - / display parameter



[Setting example] Displaying ON-delay alarm or the remaining time of timers -

| Display | Operating procedure |
|------------------------------|---|
| 1499 1500 57 by 6FF | 1. Press and hold the SEL key for one second. 5769 will be displayed. |
| ΓΠ- 1 10 | 2. Press the key to display Π - 1. The remaining time of timer 1 will be displayed. |
| ΓΠ-2 8 | 3. Press the \bigcirc or \bigcirc keys to display the remaining time of $\lceil \Pi - I, \lceil \Pi - I \rceil$ and $\lceil \Pi - I \rceil$. |
| 1499 1500 | 4 If you want to display the operation status, press and hold the SEL key for two seconds. |

Setting alarm
1, 2 and 3
Upper limit of alarm
1, 2 and 3
Upper limit of alarm
1, 2 and 3
Upper limit of alarm
1, 2 and 3
Lower limit of alarm 1,2 and 3
(Option)

(Setting range:
Absolute value alarm: 0 to 100%FS
(Option)

[Description] -

- These parameters are used to for settings of alarm 1, 2 and 3
- When the alarm type (RL \(\Pi\) 1, RL \(\Pi\)2 or RL \(\Pi\)3) is set to 0 to 15, alarms 1, 2 and 3 (RL 1, RL \(\Pi\) and RL \(\Pi\)) can be set.
- When the alarm type (RL \(\Pi\) 1, RL \(\Pi\)2 or RL \(\Pi\)3) is set to any value other than 0 to 15, the upper and lower limits of alarm 1, 2 and 3 (R 1-H, R2-H, R3-H, R 1-L, R2-L, R3-L) can be set.

[Note]

Setting codes (12 to 15) cannot be selected in alarm type 1 and 3 ($RL\Pi I/RL\Pi 3$).

Related parameters: RLN I, RLN2, RLN3 (page 46)
R Ih4, R2h4, R3h4 (page 59)
dL4 I, dL42, dL43 (page 55)
R IoP, R2oP, R3oP (page 60)

[Setting example] Setting the operation value of alarm 2 to -10°C ———

| Display | Operating procedure |
|--------------------------------|---|
| 1499 1500 5F b y 6F F | 1. Press and hold the SEL key for one second. 5. Ly will be displayed on the PV display. |
| RL 2 | 2. Press the key to display #L 2. |
| - <u>;</u> @- | 3. Press the SEL key once. The current setting (II) flashes on the SV display. |
| in- | 4. Press the or keys to display - 10. |
| RL 2 - 10 | 5. Press the <u>SEL</u> key once ID will stop flashing and will be registered for RL2. After that, the controller will operate with the operation value of alarm 2 being -10°C. |
| 1499 1500 | 6. If you want to display the operation status, press and hold the SEL key for two seconds. |

Lo[Key lock (Setting range: 0-5)

[Description] -

- This parameter makes the set values of parameters unchangeable. However, the parameter name and the set values can be displayed.
- To reset the key lock, change to [].
- Even when the key lock is set, control and alarm functions can operate properly.
- There are six levels of the key lock:
 - #: Unlocked (reset)
 - ! : All settings are unchangeable from the controller, but changeable via communication.
 - 2: Only the SV is changeable from the controller, and all settings are changeable via communication.
 - 3: All settings are changeable from the controller, but unchangeable via communication.
 - 4: All settings are unchangeable from the controller or via communication.
 - **5** : Only the SV is changeable from the controller, but all settings are unchangeable via communication.

[Setting example] Setting the key lock to "2"

| Display | Operating procedure |
|--------------------------------|---|
| 1499 1500 5F b y 6F F | 1. Press and hold the SEL key for one second. 5. 6.4 will be displayed on the PV display. |
| LoC | 2. Press the key to display Lot. |
| -,Q- | 3. Press the SEL key once. The current setting (1) flashes on the SV display. |
| Lat | 4. Press the or week keys to display ع. |
| LoC | 5. Press the <u>SEL</u> key once. Z will stop flashing and will be registered for <u>LoC</u> . After that, any setting other than the SV cannot be changed from the front panel. |
| 1499 1500 | 6. If you want to display the operation status, press and hold the SEL key for two seconds. |



Proportional band (Setting range: 0.0 to 999.9% of the measured range)

[Description] -

- To select the ON/OFF control (two-position control), set P to 0.0. It is not necessary to set \vec{L} and \vec{d} .
- **P** can be automatically set by the auto-tuning operation.
- When P is too small, control will be unstable, and when P is too large, the response will be delayed.
- Set the hysteresis of the ON/OFF control (two-position control) in the parameter #45.
- If auto-tuning is run after the ON/OFF control is selected, the ON/OFF control changes to the PID control. To keep the ON/OFF control selected, do not execute the autotuning.

[Setting example] Changing the proportional band from 5.0% to 15.0% -

| Display | Operating procedure |
|-------------------------|--|
| 1499 1500 P 50 | 1. Press and hold the SEL key for three seconds. P will be displayed on the PV display. |
| - <u>,50</u> - | 2. Press the SEL key once. The current setting (5.7) flashes on the SV display. |
| <i>P</i> -)50}- | 3. Press the or keys to display 15. |
| P (50) | 4. Press the <u>SEL</u> key once. 150 will stop flashing and will be registered for P . After that, the controller will operate with P being 15.0%. |
| 1499 1500 | 5. If you want to display the operation status, press and hold the <u>SEL</u> key for two seconds. |



Integral time (Setting range: 0 to 3200 seconds)

[Description] —

- L can be set automatically by the auto-tuning operation.
- Z can also be set manually.

- When ζ is set to 0, the integral operation does not start.
- When **P** is set to 0.0, this makes the setting of **L** ineffective.

[Setting example] Changing the integral time from 240 seconds to 600 seconds

| Display | Operating procedure |
|-------------------------|--|
| 1499 1500 P 50 | 1. Press and hold the <u>SEL</u> key for three seconds. p will be displayed on the PV display. |
| -> 4 <u>0</u> | 2. Press the key to display . 3. Press the SEL key once. The current setting (240) flashes on the SV display. |
| -> <u>ö</u> ğ | 4. Press the or keys to display 500. 5. Press the SEL key once. 500 will stop flashing and will be registered for . After that, the controller will operate with being 500 seconds. |
| 1499 1500 | 6. If you want to display the operation status, press and hold the SEL key for two seconds. |



Derivative time (Setting range: 0.0 to 999.9 seconds)

[Description] -

- d can be set automatically by the auto-tuning operation.
- d can also be set manually.

- When d is set to 0, the differential operation does not start.
- When P is set to 0.0, this makes the setting of d ineffective.

[Setting example] Changing the differential time from 60.0 seconds to 50.0 seconds —

| Display | Operating procedure |
|-------------------------|--|
| 1499 1500 P 50 | 1. Press and hold the SEL key for three seconds. p will be displayed on the PV display. |
| <u>₽</u> | 2. Press the key to display d. 3. Press the SEL key once. The current setting (EDD) flashes on the SV display. |
| -> ad -> ad 5 ad | 4. Press the or keys to display 500. 5. Press the SEL key once. 500 will stop flashing and will be registered for d. After that, the controller will operate with d being 50.0 seconds. |
| 1499 1500 | 6. If you want to display the operation status, press and hold the <u>SEL</u> key for two seconds. |



Hysteresis range for ON/OFF control (Setting range: 0 to 50%FS)

[Description] -

• To select the ON/OFF control (two-position control), set P to 0.0. It is not necessary to set \vec{L} and \vec{d} .

• When the hysteresis range (Range of ON/OFF control) is too small, the output may switch the ON/OFF frequently. (This may affect the life of the device to be controlled, especially when contact output is selected.)

• The unit of the set value of this parameter is °C or °F (engineering unit). The setting range varies according to the measured range of input.

[Ex] Input Thermocouple K: At measured range of θ

to 400 °C, the setting range is 0 to 200 °C.

: At measured range of 0 Resistance bulb

> to 150 °C, the setting range is 0 to 75 °C.

P (page 24) Related parameters:

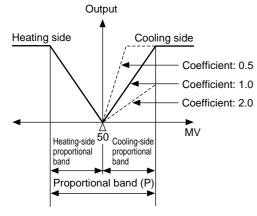
anaF (page 36)

[Setting example] Changing the hysteresis range from 1°C to 35°C -

| Display | Operating procedure |
|-------------------------|--|
| 1499 1500 P 50 | 1. Press and hold the SEL key for three seconds. P will be displayed on the PV display. |
| H422 | 2. Press the key to display #35. |
| H42 | 3. Press the SEL key once. The current setting (!) flashes on the SV display. |
| - <u>3</u> 2 | 4. Press the or keys to display 35. |
| #45 35 | 5. Press the <u>SEL</u> key once. 35 will stop flashing and will be registered for HY5. After that, the controller will operate with the hysteresis range being 35°C. |
| 149 <u>9</u> 1500 | 6. If you want to display the operation status, press and hold the SEL key for two seconds. |

[Description]

• This parameter is used for setting the cooling-side proportional band. (See the figure below.)



• Before setting the cooling-side proportional band, set the heating-side proportional band to an optimum value. To select the two-position control for the cooling side, set [aal to 0.0.

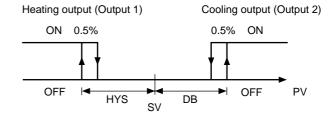
Cooling-side proportional band
$$= \frac{\text{Proportional band (P)}}{2} \times \text{Coefficient}$$

Ex) When making the proportional band of 10% of the full scale with the proportional band (P) being 50%:

$$10\% = \frac{50\%}{2} \times \text{Coefficient}$$

Consequently, the coefficient is 0.4.

• When P is set to 0.0 and Cool is set to 0.0 in the dual output type, the cooling output is as shown in the figure below. The hysteresis is fixed at 0.5% FS.



Related parameters: #45 (page 27)

(page 24)

(page 29)

[Setting example] Changing the cooling-side proportional band coefficient from 1.0 to 2.5 —

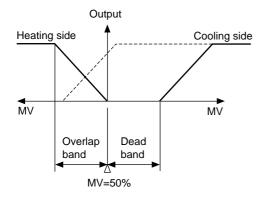
| Display | Operating procedure |
|-------------------------|--|
| 1499 1500 P 50 | 1. Press and hold the SEL key for three seconds. P will be displayed on the PV display. |
| Cool (0 | 2. Press the key to display [ool . |
| [o q l -)[j] | 3. Press the SEL key once. The current setting (!!) flashes on the SV display. |
| Look | 4. Press the or keys to display 25. |
| Cool 25 | 5. Press the <u>SEL</u> key once. 25 will stop flashing and will be registered for <u>Lool</u> . After that, the controller will operate with the cooling-side proportional band coefficient being 2.5. |
| 1499 1500 | 6. If you want to display the operation status, press and hold the SEL key for two seconds. |

Cooling-side proportional band shift (Dead band/Overlap band)

(Option: Available for DUAL output only) (Setting range: -50.0 to +50.0)

[Description] -

• This parameter is used for shifting the cooling-side proportional band from the set value. (See the figure below.)



- When db is a positive value, it is called the "Dead band", and when it is a negative value, the "Overlap band".
- Since the unit of db is same one used for MV [%], if you want to set db in the unit of deviation [%], db must be converted using the equation below.

DB [%] = Deviation
$$\times \frac{100}{P}$$
 [%]

Ex) When making a dead band with a deviation of 1.0 [%] from the SV while the proportional band (P) is 5.0%:

DB [%] =
$$1.0 \times \frac{100}{5.0} = 20$$
 [%]

Consequently, set the parameter db to 20 [%].

• Related parameters: **P** (page 24)

[Setting example] Shifting the cooling-side proportional band by 2.0 -

| Display | Operating procedure |
|-------------------------|---|
| 1499 1500 P 50 | 1. Press and hold the <u>SEL</u> key for three seconds. P will be displayed on the PV display. |
| db 00 | 2. Press the key to display db. |
| - <u>71</u> f- | 3. Press the SEL key once. The current setting ([][]) flashes on the SV display. |
| dp TH | 4. Press the or keys to display ביים . |
| db 20 | 5. Press the <u>SEL</u> key once. 20 will stop flashing and will be registered for db. After that, the controller will operate with db being 2.0 %. |
| 1499 1500 | 6. If you want to display the operation status, press and hold the SEL key for two seconds. |

♣RL Output offset value (Setting range: -100.0 to 100.0 %)

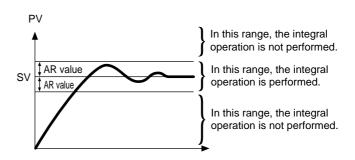
Anti-reset windup (Setting range: 0 to 100%FS)

[Description] -

The anti-reset windup (Rr) is automatically set to an optimum value by the auto-tuning operation.
 By setting bRL, the amount of overshoot can be adjusted.

[Note]

By making use of the fuzzy control system equipped with PXR, the amount of overshoot can be minimized without setting hRL and Rr.



[Setting example] Changing the anti-reset windup from 60°C to 80°C. -

| Display | Operating procedure |
|-------------------------|---|
| 1499 1500 P 50 | 1. Press and hold the <u>SEL</u> key for three seconds. P will be displayed on the PV display. |
| Rr 60 | 2. Press the $	extstyle 	extstyle$ |
| Rr -50± | 3. Press the SEL key once. The current setting (50) flashes on the SV display. |
| ₽r -80} | 4. Press the or keys to display 80. |
| Rr 80 | 5. Press the \boxed{SEL} key once. \cancel{BD} will stop flashing and will be registered for \cancel{Rr} . After that, the controller will operate with the anti-reset windup being 80°C. |
| 1499 1500 | 6. If you want to display the operation status, press and hold the <u>SEL</u> key for two seconds. |

Control algorithm (Settings: PID/FUZY/SELF)

[Description] -

- This parameter is used for selecting PID control, FUZZY-PID control, or PID control with self-tuning.
- To select the PID control or FUZZY-PID control, it is necessary to set the parameters of P, $\vec{\iota}$, \vec{d} , and Rr manually or by the auto-tuning in advance.
- For the ON/OFF control (Two-position control), select the PID control and then set *P* to 0.0. For detailed information, refer to *P* (page 24).
- Refer to the next page for the PID control with self-tuning.

[Setting example] Changing the control system from PID to FUZZY -

| Display | Operating procedure |
|-------------------------|---|
| 1499 1500 P 50 | 1. Press and hold the SEL key for three seconds. P will be displayed on the PV display. |
| Errl Pid | 2. Press the key to display [[r]. |
| | 3. Press the SEL key once. The current setting (Pid) flashes on the SV display. |
| [[r l -FU24 | 4. Press the or keys to display בּנֵבֶץ. |
| [[rL FUZY | 5. Press the <u>SEL</u> key once. FUZY will stop flashing and will be registered for <u>LfrL</u> . After that, the controller will operate with the FUZZY control system activated. |
| 1499 1500 | 6. If you want to display the operation status, press and hold the SEL key for two seconds. |

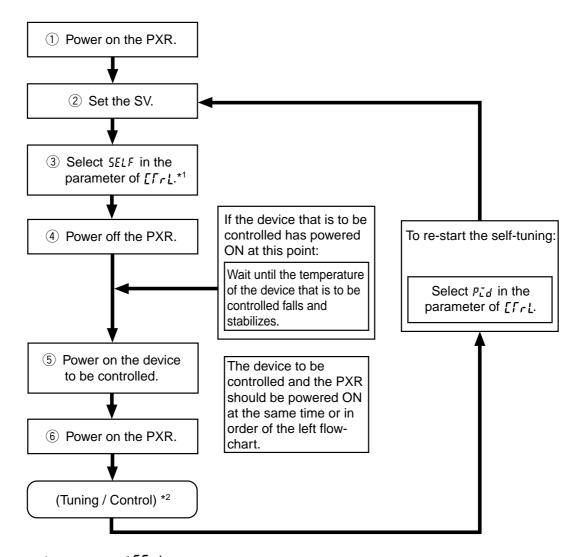
[Self-tuning] -

1 Function:

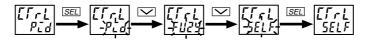
With the self-tuning function, PID parameters are automatically re-optimised depending on the actual condition of device to be controlled and the setting temperature (SV).

2 How to execute:

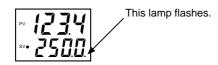
Follow the procedure shown below to set and execute the self-tuning. The self-tuning starts to run at the appropriate conditions. (See page 31)



*1: How to set the parameter of $[\Gamma, \Gamma]$:



*2: Display during self-tuning is shown below:



- 3 Conditions under which the self-tuning runs:
 - 1 At power-on:

The self-tuning runs when all of the following conditions are met.

- The SV that appears at power-on is not the same one when the P, \vec{L} , \vec{d} , and \vec{R}_{r} were set previously. (i.e. the P, \vec{L} , \vec{d} , and \vec{R}_{r} set by the self-tuning, auto-tuning, manual setting, and writing by communications tools at previous time)
- The (SV-PV) at power-on is larger than (the value of $P \times$ input range) or (the set value of $S \downarrow F b$).
- 2 When the SV is changed:

The self-tuning runs when all the conditions below are met.

- The changed SV is larger than the SV that was set when the P, \vec{L} , \vec{d} , and \vec{R}_{r} were selected previously.
- The changed amount of the SV is larger than 0.
- The changed amount of the SV is larger than (the set value of $P \times \text{input range}$) or (the set value of $5 \angle Fb$).
- 3 When output becomes unstable:

The self-tuning runs when control becomes unstable and the hunting of the operating output (MV) occurs. (The self-tuning runs only once as long as the SV is not changed.)

4 When the control standby mode is cancelled:

The self-tuning runs by the same reason as "① At power-on" are met.

* Only when the PXR is set to standby mode at power-on.

4 Conditions under which the self-tuning does not run:

- 1 During control standby mode
- 2 During two-position control (Parameter of P = 0)
- 3 During auto-tuning operation
- 4 During ramp-soak operation
- 5 Error display (LLLL or [][][] is displayed.)
- 6 During dual output (The set value of the parameter of P n) is larger than 4.)
- \bigcirc When setting the parameters of P, \vec{L} , \vec{d} , and \vec{R}_r manually (including the setting written by communications tools)

5 Conditions under which the self-tuning is suspended:

- 1 At the condition described in 4 shown above
- 2 When the SV is changed during self-tuning operation
- ③ When the self-tuning operation can not be completed within approx. 9 hours

6 Caution

- ① Once the PID constant is set, the self-tuning does not operate at next power-on as long as the SV is not changed.
- ② For an accurate tuning, be sure to power on the device to be controlled before or at the same time as the PXR is powered on. If the PXR has to be powered on first for reasons of the system configuration, perform the auto-tuning with the PID or FUZZY control.
- ③ If the device to be controlled is powered on under temperature change (especially when it rises), accurate tunings can not be performed. Be sure to power on the PYX when the temperature of device to be controlled is stabilized.
- ④ The self-tuning does not run for cooling system control under Direct Action output (Parameter P n I = 2 or 3).
- (5) In case the control is not stable after performing the self-tuning, change the algorithm to the PID or FUZZY control and perform the auto-tuning.

7 Reference [About the self-tuning method]

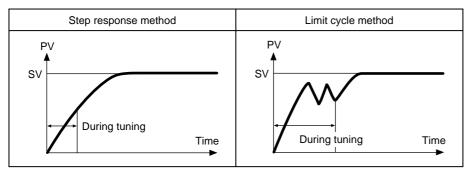
The PID constant is calculated in one of the following two methods.

The method is selected automatically depending on the characteristics of the device to be controlled.

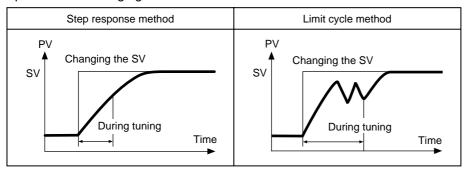
- Step response method
- Limit cycle method

The following figures show the operations at power-on and changing the SV, and under unstable control.

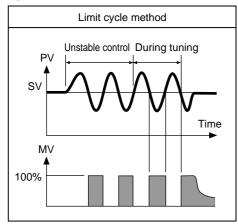
① Operations at power-on



2 Operations at changing the SV



3 Operation under unstable control





5LFb PV (Measured value) stable range (Setting range: 0 to 100%FS)

[Description] -

- Self-tuning logic recognizes that control is stable if PV is staying within the SV \pm 5LFL.
- It is not necessary to set this parameter under normal conditions.

[Setting example] Changing the PV stable range from 2 to 3 —

| Display | Operating procedure |
|-------------------------|---|
| 1499 1500 P 50 | 1. Press and hold the SEL key for three seconds. P will be displayed on the PV display. |
| SLFb | 2. Press the key to display 51. Fb. |
| SLFb -2 | 3. Press the SEL key once. The current setting () flashes on the SV display. |
| 5LFb 31- | 4. Press the or keys to display 3. |
| SLFb 3 | 5. Press the <u>SEL</u> key once. 3 will stop flashing and will be registered for 5½ Fb. After that, the controller will operate with the PV range being 3. |
| (499 (500 | 6. If you want to display the operation status, press and hold the SEL key for two seconds. |

DNDF HYS (Hysteresis) mode at ON/OFF control (Settings: oFF/on)

[Description] -

- This parameter is used for selecting the hysteresis operation mode at ON/OFF control.
 - oFF: Starts the ON/OFF control at the values of SV+ $\frac{HYS}{2}$ and SV- $\frac{HYS}{2}$.
 - on: Starts the ON/OFF control at the values of SV and SV+HYS, or SV and SV-HYS.
- Default setting: ON

| | onoF : OFF | onoF : ON |
|----------------|------------|-----------|
| Reverse action | HYS | HYS |
| Direct action | HYS | HYS SV |

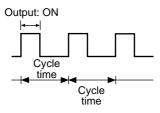
[Setting example] Setting the hysteresis mode to ON

| Display | Operating procedure |
|-------------------------|--|
| 1499 1500 P 50 | 1. Press and hold the SEL key for three seconds. P will be displayed on the PV display. |
| anaF aFF | 2. Press the key to display anof. |
| onaf -pff; | 3. Press the \boxed{SEL} key once. The current setting ($_{\alpha}FF$) flashes on the SV display. |
| - <u>-</u> -o | 4. Press the key to display an. |
| anaF an | 5. Press the <u>SEL</u> key once. an will stop flashing and will be registered for ana F. After that, the controller will operate with the hysteresis being as shown in the figure of ON above. |
| 1499 1500 | 6. If you want to display the operation status, press and hold the <u>SEL</u> key for two seconds. |

Cycle time of control output 1 (Setting range: 1 to 150 seconds)

[Description] -

- This parameter is applicable for to the contact output and SSR-driving output.
- While input is within the proportional band, output changes between ON and OFF in cycles. These cycles are called cycle time.



• Do not set this parameter to "0".

For contact output:

The higher the frequency of output is, the more precise the control becomes. However a high frequency of output may shorten the life of the contacts and the device to be controlled. Be sure to adjust the proportional cycles considering controllability and the life of the device and the contacts.

Typical: 30 seconds

For SSR-driving output:

Use in short cycles if there is no problem with the device to be controlled.

Typical: 1 to 2 seconds

[Setting example] Setting the cycle time from 30 seconds to 20 seconds -

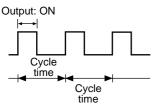
| Display | Operating procedure |
|-------------------------|--|
| 1499 1500 P 50 | 1. Press and hold the <u>SEL</u> key for three seconds. p will be displayed on the PV display. |
| 7.C 30 | 2. Press the key to display $f \xi$. |
| 拉 | 3. Press the SEL key once. The current setting (30) flashes on the SV display. |
| <u> </u> | 4. Press the or we key to display والم |
| [20] | 5. Press the <u>SEL</u> key once. Zn will stop flashing and will be registered for <u>F</u> . After that, the controller will operate with the cycle time being 20 seconds. |
| 1499 1500 | 6. If you want to display the operation status, press and hold the SEL key for two seconds. |



Cycle time of control output 2 (Cooling-side)
(Setting range: 1 to 150 seconds) (Option: Available for DUAL output only)

[Description] -

- By this parameter is set, the cycle time of control output 2.
- While input is within the proportional band, output changes between ON and OFF in cycles. These cycles are called cycle time.



• Do not set this parameter to "0".

For contact output:

The higher the frequency of output is, the more precise the control becomes. However a high frequency of output may shorten the life of the contacts and the device to be controlled. Be sure to adjust the proportional cycles considering controllability and the life of the device and the contacts.

Typical: 30 seconds

[Setting example] Setting the cooling-side cycle time from 30 seconds to 20 seconds -

| Display | Operating procedure |
|-------------------------|---|
| 1499 1500 P 50 | 1. Press and hold the <u>SEL</u> key for three seconds. p will be displayed on the PV display. |
| 7[2 30 | 2. Press the key to display $f[]$. |
| - <u>7</u> [1 | 3. Press the SEL key once. The current setting (30) flashes on the SV display. |
| 7 <u>4</u> | 4. Press the or key to display 20. |
| 70 70 | 5. Press the <u>SEL</u> key once. 20 will stop flashing and will be registered for FL2 . After that, the controller will operate with the cooling-side cycle time being 20 seconds. |
| 1499 1500 | 6. If you want to display the operation status, press and hold the SEL key for two seconds. |

P-n2 Input signal code (Setting range: 0 to 16)

[Description] -

• This parameter is used for selecting input signals. Input signal varies depending on the sensors (2 types below). Set a code that corresponds to the sensor you use.

> Type I : Thermocouples (9 kinds of signals) Resistance bulbs (1 kind of signal)

: Voltage, current Type II

- Input signals can be selected within the same type. It is impossible to select input signals of a different type.
- For type II, to change from the voltage input to the current input, connect the supplied resistance of 250Ω between terminals 17 and 18 (in the case of PXR4), and between terminals 35 and 36 (in the case of PXR5/9), in addition to changing the code.

When changing from the current input to the voltage input, remove the resistance of 250 Ω as well as changing the code.

- · Input signals and codes
- 1 Input signals code table

| Туре | Input signal | Code |
|------|------------------------|------|
| | Resistance bulb (RTD) | |
| | • Pt 100 | 1 |
| | Thermocouple | |
| | • J | 2 |
| | •K | 3 |
| | • R | 4 |
| I | •B | 5 |
| | •S | 6 |
| | •T | 7 |
| | •E | 8 |
| | • N | 12 |
| | • PL-II | 13 |
| II | 1 to 5 V, 4 to 20mA DC | 16 |

[Note]

After changing the codes, power off the PXR, and then power it on again.

[Setting example] Changing from thermocouple K to thermocouple T in Type I -

| Display | Operating procedure |
|-------------------------|---|
| 1499 1500 P 50 | 1. Press and hold the <i>SEL</i> key for three seconds. **P will be displayed on the PV display. |
| P-n2 | 2. Press the key to display $P - nZ$. |
| P - 12 | 3. Press the SEL key once. The current setting (3) flashes on the SV display. |
| P-n2 | 4. Press the or key to display 7. |
| P-n2 | 5. Press the <u>SEL</u> key once. 7 will stop flashing and will be registered for $P - nQ$. After that, the controller will operate with the kind of input signals being thermocouple T. |
| 1499 1500 | 6. If you want to display the operation status, press and hold the SEL key for two seconds. |

P-5L

Setting the measuring range (Input range) (Setting range: -1999 to 9999)

P-5U

P-F

Selection °C / °F (Settins: °C / °F)

[Description]

- These parameters are used for setting the lower and upper limits of the measured range and unit of temperature.
- A decimal point position can be set in the parameter of P-dP.
- For the current and voltage inputs, \square , ! and ! can be set for P dP, and for other inputs, \square and ! can be set for P dP.
- See the right table for input range.

2 Input range table (Standard range)

| | | Range | | ge | With / without | R | ang | ge | With / without |
|----------------|-------------|-----------------------|----|------|-----------------|------|------|------|-----------------|
| Input type | | (°C) | |) | a decimal point | | (°F) |) | a decimal point |
| | | | | | (°C)* | | | | (°F)* |
| | | 0 | to | 150 | 0 | 32 | to | 302 | 0 |
| | | 0 | to | 300 | 0 | 32 | to | 572 | 0 |
| Resistance | | 0 | to | 500 | 0 | 32 | to | 932 | 0 |
| bulb JIS | Pt100Ω | 0 | to | 600 | 0 | 32 | to | 1112 | X |
| (IEC) | | -50 | to | 100 | 0 | -58 | to | 212 | 0 |
| | | -100 | to | 200 | 0 | -148 | to | 392 | 0 |
| | | -199 | to | 600 | 0 | -328 | to | 1112 | X |
| | | -199 | to | 850 | Х | -328 | to | 1562 | Х |
| | J | 0 | to | 400 | 0 | 32 | to | 752 | 0 |
| | J | 0 | to | 800 | 0 | 32 | to | 1472 | X |
| | K | 0 | to | 400 | 0 | 32 | to | 752 | 0 |
| | K | 0 | to | 800 | 0 | 32 | to | 1472 | X |
| | K | 0 | to | 1200 | Х | 32 | to | 2192 | X |
| | R | 0 | to | 1600 | Х | 32 | to | 2912 | Х |
| Thermocouple | В | 0 | to | 1800 | Х | 32 | to | 3272 | X |
| | S | 0 | to | 1600 | Х | 32 | to | 2912 | X |
| | Т | -150 | to | 200 | 0 | -238 | to | 392 | Х |
| | Т | -150 | to | 400 | 0 | -238 | to | 752 | X |
| | Е | 0 | to | 800 | 0 | 32 | to | 1472 | X |
| | E | -150 | to | 800 | 0 | -238 | to | 1472 | Х |
| | N | 0 | to | 1300 | Х | 32 | to | 2372 | X |
| | PL-II | 0 | to | 1300 | Х | 32 | to | 2372 | X |
| Direct-current | | -1999 to 9999 | | | | | | | |
| voltage | 1 to 5 V DC | (Scaling is possible) | | | | | | | |
| * 0 " | | | | | | | | | |

^{*} O: with X: without

[Note]

The input accuracy is $\pm 0.5\% FS \pm 1$ digit except the cases shown below.

Thermocouple R at 0 to 500 °C: In this range, this controller may display a wrong process value because of the characteristecs of the sensor.

Other kinds of thermocouples: $\pm 0.5\%$ FS ± 1 digit ± 1 °C

^{*} For 4 to 20mA DC input, connect the supplied resistance of 250Ω between terminals 1 and 18 (in the case of PXR4), and between terminals 35 and 36 (in the case of PXR5/9) to change to the 1 to 5V DC input.

[Setting example] Changing the measuring range from 0°C to 150°C to -100°C to 200°C (Pt100) ——

| Display | Operating procedure |
|-------------------------|---|
| 1499 1500 P 50 | 1. Press and hold the <u>SEL</u> key for three seconds. P will be displayed on the PV display. |
| P-51 | 2. Press the key to display $P-5L$. |
| P-51 -0- | 3. Press the SEL key once. The current setting (1) flashes on the SV display. |
| P - 51 100 | 4. Press the or key to display - ([[[]]. |
| P - 51 - 100 | 5. Press the SEL key once (DD) will stop flashing and will be registered for P-51. |
| P - 5U 150 | 6. Press the key to display P-511 on the PV display. |
| P - 511 -150 | 7. Press the SEL key once. The current setting (150) flashes on the SV display. |
| P - 5U -200 | 8. Press the or key to display 200. |
| P-5U 200 | 9. Press the SEL key once. 200 will be registered for P-5 11. After that, the controller will operate with the measured range being -100°C to 200°C. |
| 1499 2000 | 10. If you want to display the operation status, press and hold the SEL key for two seconds. |

P-dP Decimal point position (Settings: 0 / 1 / 2)

[Description] -

• This parameter is used for selecting the number of decimal point positions for the PV (Measured value).

Related parameters: **P-5L** (page 40) **P-5**!! (page 40)



- "0" (No digit after decimal point)

- "1" (1 digit after decimal point)

- "2" (2 digit after decimal point. This is valid only for the voltage and current inputs)

[Setting example] Changing the decimal point position setting from 0 to 1-

| Display | Operating procedure |
|-----------------------|--|
| 150 150 P 50 | 1. Press and hold the <u>SEL</u> key for three seconds. p will be displayed on the PV display. |
| P - dP | 2. Press the \bigvee key to display $P - dP$. |
| P - dP -,Q- | 3. Press the SEL key once. The current setting ([]) flashes on the SV display. |
| P-dP - !! | 4. Press the key to display !. |
| P-dP | 5. Press the <u>SEL</u> key once. I will stop flashing and will be registered for P-dP . After that, the controller will operate with one decimal point position displayed. |
| 1499 1500 | 6. If you want to display the operation status, press and hold the <i>SEL</i> key for two seconds. |



PV (Measured value) offset (Setting range: -10 to 10%FS)

[Description]

- With this function, predetermined value is added to the input reading. This parameter is used for adjusting PXR's indication so that it becomes same as the one of the other instruments like recorder.
- The PXR operates at the displayed PV (the value to which the PV offset value is added).

[Setting example] Adding the PV offset value of 5°C to the input value of 1200 °C -

| Display | Operating procedure |
|-------------------------|---|
| 1200 1200 P 50 | 1. Press and hold the SEL key for three seconds. p will be displayed on the PV display. |
| PUOF O | 2. Press the key to display Punf. |
| РИО <u>Г.</u> Ф. | 3. Press the SEL key once. The current setting ([]) flashes on the SV display. |
| PUOF | 4. Press the or key to display 5. |
| PUOF 5 | 5. Press the <u>SEL</u> key once. 5 will stop flashing and will be registered for PUGF . After that, the controller will operate so that the value to which the offset value of 5°C is added can be brought close to the set value. |
| 1205 1200 | 6. If you want to display the operation status, press and hold the SEL key for two seconds. |



SV (Setting value) offset (Setting range: -50 to 50%FS)

[Description] -

- With this function, predetermined value is added to the original SV. This parameter is used to eliminate the offset that occurs in performing P control.
- The PXR operates based on the SV to which the SV offset value is added.
- Alarm judgment is made by the displayed SV to which the SV offset value is not added.

[Setting example] Adding the SV offset value of 9°C to the currently set value —

| Display | Operating procedure |
|-------------------------|---|
| 1499 1500 P 50 | 1. Press and hold the SEL key for three seconds. p will be displayed on the PV display. |
| 5U0F 0 | 2. Press the key to display 5UDF. |
| 500F | 3. Press the SEL key once. The current setting ([]) flashes on the SV display. |
| 5UQF - 9- | 4. Press the or key to display 9. |
| SUOF S | 5. Press the <u>SEL</u> key once. 9 will stop flashing and will be registered for 5UDF . (The displayed SV remains unchanged.) After that, the controller will operate at the SV value to which the SV offset value of 9°C is added. |
| 1499 1500 | 6. If you want to display the operation status, press and hold the SEL key for two seconds. |

P-dF Time constant of input filter (Setting range: 0.0 to 900.0 seconds)

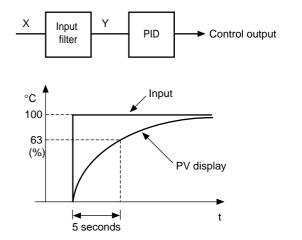
[Description] -

• This parameter are used for reducing the fluctuation of input signal (filter function).

For example, when the input filter constant is set to 5 seconds, the PV changes as shown in right figure while input changes from 0 to 100% suddenly. It takes 5 seconds for the PV to change from 0 to 63.2%.

[Note]

The factory default setting is 5.0 (5 seconds). Do not change this parameter as long as changing is not of absolute necessity.



[Setting example] Changing the filter constant from 5.0 (5 seconds) to 10.0 (10 seconds) -

| Display | Operating procedure |
|-------------------------|---|
| 1499 1500 P 50 | 1. Press and hold the SEL key for three seconds. p will be displayed on the PV display. |
| P - dF 50 | 2. Press the key to display P-dF. |
| P - dF -50}- | 3. Press the SEL key once. The current setting (5.17) flashes on the SV display. |
| P - dF -)001 | 4. Press the or key to display IDD. |
| P-dF 100 | 5. Press the <u>SEL</u> key once. [III] will stop flashing and will be registered for P-dF . After that, the controller will operate with the filter constant being 10.0. |
| 1499 1500 | 6. If you want to display the operation status, press and hold the SEL key for two seconds. |

Alarm types (Setting range: 0 to 34) (Option)

[Description]

- These parameters are used for selecting the operation types of Alarms 1, 2 and 3.
- ALT for ALT3 is activated in the same way as ALT2 except for codes 12 to 15. (Codes 12 to 15 cannot be selected for ALT1 and ALT3.)
- When any code of 12 to 15 is selected for Alarm 2, Alarm 2 is activated and Alarm 1 or Alarm 3 is cancelled. "Alarm hysteresis", "Delay time", and "Alarm latch" can be selected in Alarm 2 settings.
- The display of the parameter in which the alarm value is set varies depending on the alarm operation types.

[Note] Alarm set value and alarm operations

| | | Alarm set value (AL) | | | |
|-------------------|----------------|----------------------|---------------|--|--|
| | | Plus setting | Minus setting | | |
| Absolute value | Upper limit | AL | Disabled | | |
| | Lower limit | AL 0 | Disabled | | |
| Deviation | Upper limit | AL SV | AL A SV | | |
| value | Lower limit | AL SV | Δ AL SV | | |

[Note]

- Since the alarm set value may change after changing the alarm operation types, be sure to set the alarm set value again.
- After changing the alarm operation types, power the PXR off, and then on.
- Setting code 0 indicates "No alarm".

Related parameters: # [hy, #2hy, #3hy (page 59)
[aP, #2aP, #3aP (page 60)
[1, #12, #13 (page 22)
[4] [1, d142, d143 (page 55)

[Setting example] Changing the alarm type of Alarm 2 from upper-limit deviation to the upper-limit deviation with hold –

| Display | Operating procedure |
|-------------------------|---|
| 1499 1500 P 50 | 1. Press and hold the SEL key for three seconds. p will be displayed on the PV display. |
| AL NZ | 2. Press the key to display RL NZ. |
| RL ((2) | 3. Press the SEL key once. The current setting (5) flashes on the SV display. |
| AL 1(2) -,8}- | 4. Press the key to display 3. |
| RLNZ 8 | 5. Press the SEL key once. B will stop flashing and will be registered for FL N2 . After that, the controller will operate with Alarm 2 of upper limit deviation with hold. |
| 1499 1500 | 6. If you want to display the operation status, press and hold the SEL key for two seconds. |

[Alarm type list] -

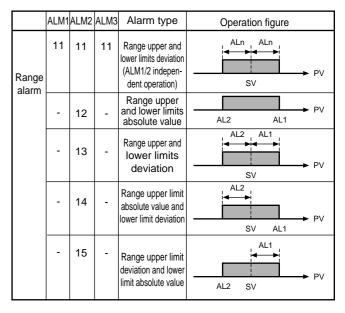
The table below shows the meaning of symbols in the following operation figures.

| | Alarm 1 | | | Alarm 2 | Alarm 3 | | |
|------------|-------------------|-------------------------------------|-------------------|-------------------------------------|-------------------|-------------------------------------|--|
| Alarm type | Display symbol | Screen name | Display symbol | Screen name | Display symbol | Screen name | |
| 0 to 15 | AL1 | Set value of Alarm 1 | AL2 | Set value of Alarm 2 | AL3 | Set value of Alarm 3 | |
| 40.4.04 | A1-L | Lower-limit of set value of Alarm 1 | A2-L | Lower-limit of set value of Alarm 2 | A3-L | Lower-limit of set value of Alarm 3 | |
| 16 to 31 | A1-H | Upper-limit of set value of Alarm 1 | A2-H | Upper-limit of set value of Alarm 2 | А3-Н | Upper-limit of set value of Alarm 3 | |

- Alarm 1 and 3 are activated in the same way as alarm 2 except codes 12 to 15. (Codes 12 to 15 cannot be selected for Alarm 1 or 3. If any of them is selected, the instrument recognizes it as code 0, "No alarm," and operates as such.)
- When any code of 12 to 15 is selected for Alarm 2, Alarm 2 is activated and Alarm 1 is not raised. "Alarm hysteresis", "Delay time", and "Alarm latch" can be selected in Alarm 2 settings.
- The display of the parameter in which the alarm value is set varies depending on the alarm operation types.
- Since the alarm set value may change after changing the alarm operation types, confirm the alarm set value. (Note that this is not abnormal.)

· Alarm codes for standard types

| | ALM1 | ALM2 | ALM3 | Alarm type | Operation figure |
|-----------------|------|------|------|--|------------------|
| | 0 | 0 | 0 | No alarm | ——— PV |
| Absolute value | 1 | 1 | 1 | Upper-limit absolute value | ALn PV |
| alarm | 2 | 2 | 2 | Lower-limit absolute value | ALn PV |
| | 3 | 3 | 3 | Upper-limit absolute value (with hold) | ALn PV |
| | 4 | 4 | 4 | Lower-limit absolute value (with hold) | ALn PV |
| Deviation value | 5 | 5 | 5 | Upper-limit deviation | SV PV |
| alarm | 6 | 6 | 6 | Lower-limit deviation | ALn PV |
| | 7 | 7 | 7 | Upper and lower limits deviation | ALn ALn PV |
| | 8 | 8 | 8 | Upper-limit deviation (with hold) | SV PV |
| | 9 | 9 | 9 | Lower-limit deviation (with hold) | ALn PV |
| | 10 | 10 | 10 | Upper and lower limits deviation (with hold) | ALN ALN PV |

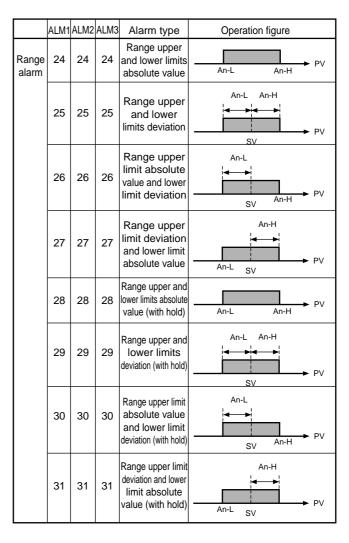


• Timer codes

| | ALM1 | ALM2 | ALM3 | Alarm type | Operation figure |
|-------|------|------|------|------------------------|---------------------|
| Timer | 32 | 32 | 32 | ON-delay timer | Di ALM dLYn |
| | 33 | 33 | 33 | OFF-delay timer | ALM dLYn |
| | 34 | 34 | 34 | ON/OFF- delay timer | Di ALM dLYn dLYn |

• Alarm codes with dual set values

| | ALM1 | ALM2 | ALM3 | Alarm type | Operation figure |
|-----------------------|------|------|------|--|--------------------|
| Upper and lower | 16 | 16 | 16 | Upper and lower limits absolute value | An-L An-H PV |
| limits alarm | 17 | 17 | 17 | Upper and lower limits deviation | An-L An-H |
| | 18 | 18 | 18 | Upper limit absolute value and lower limit deviation | An-L SV An-H PV |
| | 19 | 19 | 19 | Upper limit deviation and lower limit absolute value | An-H An-L SV |
| | 20 | 20 | 20 | Upper and lower limits absolute value (with hold) | An-L An-H PV |
| | 21 | 21 | 21 | Upper and lower limit deviation (with hold) | An-L An-H |
| | 22 | 22 | 22 | Upper limit absolute value and lower limit deviation (with hold) | An-L SV An-H PV |
| | 23 | 23 | 23 | Upper limit deviation and lower limit absolute value (with hold) | An-H PV An-L SV |



dLYn: The delay time of Alarms 1, 2 and 3 or timers 1, 2 and 3

ALn: The set value of Alarms 1, 2 and 3

An-L: The set value (lower limit) of Alarms 1, 2 and 3 $\,$

An-H: The set value (upper limit) of Alarms 1, 2 and 3

AL1: The set value of Alarm 1

AL2: The set value of Alarm 2

AL3: The set value of Alarm 3

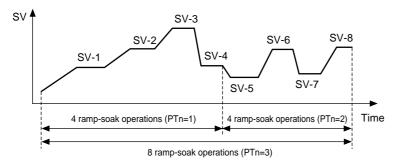
Prn | Selecting ramp-soak patterns (Settings: 1 / 2 / 3) (Option)

[Description] -

- This parameter becomes effective when the ramp-soak operation is changed from oFF to rlin.
- Setting range
 - ! : Performs 1st to 4th segments.
 - : Performs 5th to 8th segments.
 - ? : Performs 1st to 8th segments.

[Note]

- This parameter is not effective if it is changed during RUN or HOLD.
- Types 1 and 2 cannot run one after another.
- Once $5\overline{u}$ { to $5\overline{u}$ 8 are set, when the SV limiter is set the set values of $5\vec{u}$ - 1 to $5\vec{u}$ - 2 are not changed, but the SV displayed during ramp-soak operation is affected by the SV limiter.



[Setting example] Changing the ramp-soak execute type from 1 to 3 -

| Display | Operating procedure |
|-------------------------|---|
| 1499 1500 P 50 | 1. Press and hold the SEL key for three seconds. p will be displayed on the PV display. |
| Pro | 2. Press the \bigvee key to display P_{Γ_n} . |
| | 3. Press the SEL key once. The current setting (!) flashes on the SV display. |
| PF.0 | 4. Press the key to display 3. |
| Pro 3 | 5. Press the SEL key once. 3 will stop flashing and will be registered for Prn. After that, the controller will operate in ramp-soak type 3 |
| 1499 1500 | 6. If you want to display the operation status, press and hold the SEL key for two seconds. |

Ramp-soak status display (Display only)

5 - 1 to 5 - 8 1st to 8th target SV (Setting range: 5 - 1 to 5 - 1) (Option)

1 to 7 - 8 1st to 8th ramp segment time (Setting range: 0 to 99h 59min) (Option)

1 to 7 - 1 to 8th soak segment time (Setting range: 0 to 99h 59min) (Option)

Ramp-soak modes (Setting range: 0 to 15) (Option)

[Description] -

- By these parameters, the SV (Set value) are automatically changed over time according to the patterns set in advance as shown in the figure below. A maximum of 8 ramp-soak segments can be set in PXR.
- The first ramp starts from the PV (Measured value) just before performing the program.
- The program can also be started at power-on automatically (Power-on start function).
- A maximum of eight ramp-soak segments can be set. It is also possible to set 4 ramp-soak segments twice instead.
- When the following parameters are changed under rampsoak operation, operation will change the patterns of the ramp-soak pattern is changed to the new setting.
 - 50 1 to 50 8
 - FN Ir to FNBr
 - [] 15 to [] 85
 - Nod

[Parameters]

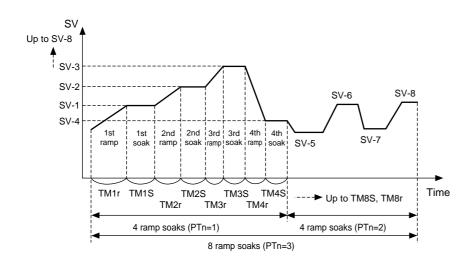
In order to execute these functions, it is necessary to set the programs in advance. To set the programs, set the SV (Setting value) and time desired for the parameters shown in the table on next page.

Related parameters: **P**[n (page 49)

ProL (page 18)

5..-**.** (page 54)

5<u>u</u> - **H** (page 54)



| Parameter display symbol | | Name | Description | Factory default settings | Remark |
|--------------------------|--------------------|------------------------------|---|--------------------------|---|
| STAT | STAT | Current program status | Displays the Ramp-soak current status. This parameter is only for display, and cannot set anything. aFF: OFF I-rP to B-rP: Under the 1st to 8th ramp operation I-5E to B-5E: Under the 1st to 8th soak operation End: Ends the program | _ | No symbol |
| 5ū-1 to 5ū-8 | SV-1 to SV-8 | 1st to 8th target SV | Sets the target value (SV) of each ramp segment (Setting range: $5\bar{u} - L$ to $5\bar{u} - H$) | 0%FS | appears when the |
| FN Ir FN8r | TM1r to TM8r | 1st to 8th ramp segment time | Sets the ramp time for each segment (Setting range: 0 to 99h 59min) | 0.00 | ramp-soak model is not selected. |
| ΓΠ 15 το ΓΠ85 | TM1s to TM8s | 1st to 8th soak segment time | Sets the soak time for each segment (Setting range: 0 to 99h 59min) | 0.00 | |
| Nod | Mod | Ramp-soak mode | Selects the modes of ramp-soak function. Set to "0" under normal conditions | 0 | |

[MODE code list]

| MOD | Power-on start | Output at the END | Output at OFF | Repeat operation |
|-----|----------------|--------------------|--------------------|------------------|
| 0 | OFF | Continuous control | | OFF |
| 1 | OFF | Continuous control | Continuous control | ON |
| | | | | |
| 2 | OFF | Continuous control | Standby mode | OFF |
| 3 | OFF | Continuous control | Standby mode | ON |
| 4 | OFF | Standby mode | Continuous control | OFF |
| 5 | OFF | Standby mode | Continuous control | ON |
| 6 | OFF | Standby mode | Standby mode | OFF |
| 7 | OFF | Standby mode | Standby mode | ON |
| 8 | ON | Continuous control | Continuous control | OFF |
| 9 | ON | Continuous control | Continuous control | ON |
| 10 | ON | Continuous control | Standby mode | OFF |
| 11 | ON | Continuous control | Standby mode | ON |
| 12 | ON | Standby mode | Continuous control | OFF |
| 13 | ON | Standby mode | Continuous control | ON |
| 14 | ON | Standby mode | Standby mode | OFF |
| 15 | ON | Standby mode | Standby mode | ON |

Power-on start Power-on Start TM1r TM1s TM2r TM2s TM3r TM3s TM4r TM4s

[Description of functions]

- 1. Power-on start: The ramp-soak operation starts to run from the current PV value.
- 2. Output at END: The output status at the END of the ramp-soak operation.
- 3. Output at OFF: The output status while the ramp-soak operation is set to OFF.
- 4. Repeat operation: This function makes the ramp-soak operation to continue after one cycle of ramp-soak operation is completed. At the event of Repeat operation: OFF, the SV that is set in the final cycle is kept.

* Standby mode: Output: control output OFF or -3%

Alarm: OFF Control: OFF

[Ramp]

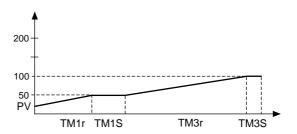
The segment in which the set value changes toward the target value.

[Soak]

The segment in which the set value is always the target value and remains unchanged.

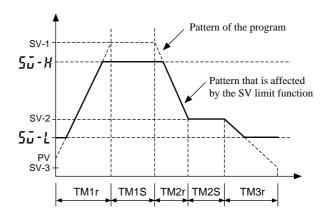
• The segment in which both the ramp time and soak time are set to "0" is skipped.

| [Ex] | | |
|-----------|-----------|-----------|
| SV-1: 50 | SV-2:200 | SV-3:100 |
| TM1r:0.10 | TM2r:0.00 | TM3r:1.00 |
| TM1S:0.05 | TM2S:0.00 | TM3S:0.75 |



• The SV limit function is valid even while the ramp-soak operation is running.

Although the set value (SV-n) remains unchanged, the SV under ramp-soak operation is affected by the limit function. Therefore, the pattern is as shown in the figure on right, and it may not change according to the original set time.



[Setting example] Setting the 1st target SV to 400°C

| Display | Operating procedure |
|-------------------------|---|
| 1499 1500 P 50 | 1. Press and hold the <u>SEL</u> key for three seconds. p will be displayed on the PV display. |
| 5ŭ - [| 2. Press the \searrow key to display $5\ddot{u}$ - 1 . |
| 5ū - / ->ū- | 3. Press the SEL key once. The current setting ([]) flashes on the SV display. |
| 5 <u>ū</u> - ! Ņģd | 4. Press the key to display 400. |
| 5ū-1 400 | 5. Press the SEL key once. 400 will stop flashing and will be registered for 50 - 1. |
| 1499 1500 | 6. If you want to display the operation status, press and hold the SEL key for two seconds. |

P-n [| Specifying control action, and output direction at input burn-out (Setting range: 0 to 19)

[Description] -

- This parameter specifies action (Single/Dual and Heating/ Cooling), and output direction at input burn-out.
- The standard model (single output) or the heating/cooling control output (dual output) are available.
- There is defference of hardware between the standard model and the heating/cooling control output model. Set the code that is applicable to your controller.
- In general, reverse action is applyed for the heating process and direct action is applyed for the cooling process.
 - * "burn-out output" means the output direction at input burn-out.
 - * The lower limit of a burn-out output indicates that output is set to OFF, or 4mA or less. The upper limit indicates that output is set to ON, or 20mA or more.

• Control operation code table

| Code | Model | Contro | l action | Burn-ou | it output* |
|--------|-----------|----------|----------|-------------|---------------|
| (P-n1) | Model | Output 1 | Output 2 | Output 1 | Output 2 |
| 0 | | Reverse | | Lower limit | |
| 1 | Standard | Reveise | | Upper limit | |
| 2 | (single) | Direct | | Lower limit | ••• |
| 3 | (Sirigio) | Direct | | Upper limit | |
| 4 | | | | Lower limit | Lower limit |
| 5 | | Reverse | | Upper limit | Lower IIIIII |
| 6 | | Reveise | Direct | Lower limit | Upper limit |
| 7 | | | | Upper limit | |
| 8 | | | Direct | Lower limit | Lower limit |
| 9 | | Direct | | Upper limit | Lower IIIIII |
| 10 | | Direct | | Lower limit | I Innar limit |
| 11 | Heating | | | Upper limit | Upper limit |
| 12 | /Cooling | | | Lower limit | Lower limit |
| 13 | (dual) | Reverse | | Upper limit | Lower IIIIII |
| 14 | | Reveise | Reverse | Lower limit | Upper limit |
| 15 | | | Keveise | Upper limit | |
| 16 | | | | Lower limit | Lower limit |
| 17 | | Direct | | Upper limit | Lower limit |
| 18 | | Direct | | Lower limit | I Innar limit |
| 19 | | | | Upper limit | Upper limit |

[Setting example] Changing the "Reverse/Lower limit for burn-out output" to the "Direct/Upper limit for burn-out output" —

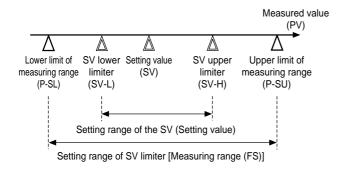
| Display | Operating procedure |
|-----------------------|---|
| 1499 1500 P-n 1 | 1. Press and hold the SEL key for five seconds. P-n ! will be displayed on the PV display. |
| P-n/ -01 | 2. Press the SEL key once. The current setting () flashes on the SV display. |
| P-n/ | 3. Press the or keys to display 3. |
| P-n ! | 4. Press the <u>SEL</u> key once. 3 will stop flashing and will be registered for P-n!. After that, the controller will operate with the "Direct/Upper limit for burn-out output" selected. |
| 1499 1500 | 5. If you want to display the operation status, press and hold the SEL key for two seconds. |

SV (Setting value) lower limiter (Setting range: 0 to 100%FS)

SV (Setting value) upper limiter (Setting range: 0 to 100%FS)

[Description]

- These parameters set the setting range of the SV (Setting value).
- Both the SV under ramp-soak operation and the SV switched by the DI1 function are affected by the SV limiter.
- The SV upper and lower limiters $(5\vec{u} H, 5\vec{u} L)$ can be set within the range of the measuring values (P - 5L, P - 5U).



[Note]

- Before setting the parameters of $5\vec{u}$ H and $5\vec{u}$ L, be sure to set the following parameters.
 - Setting the lower limit of the measured range (P 51)
 - Setting the upper limit of the measured range (P 511)
 - Setting the of decimal places point position (P dP)
- After changing the parameters of P-51, P-511, and P - dP, power off the PXR, and then on. Then, set the parameters of $5\vec{u}$ - H and $5\vec{u}$ - L again.
- Before setting the SV, set the parameters of $5\overline{\mu}$ H and 5ū-L.
- Be sure to set the values of $5\vec{u}$ H and $5\vec{u}$ L so that $5\vec{u}$ His larger than $5\vec{u} - \vec{L}$ or $5\vec{u} - \vec{H}$ is the same as $5\vec{u} - \vec{L}$.
- · Although the displayed SV is affected by the limiter immediately after setting $5\bar{u}$ - H and $5\bar{u}$ - L, the set values of $5\vec{u}$ - i to $5\vec{u}$ - i are not affected.
- When the SV limiter is set during ramp-soak operation or switching the SV with the DI1 function, the SV (SV0) that is set manually and the displayed SV are affected by the SV limiter. So, after setting the ramp-soak operation to OFF, or returning the switched SV to the original SV, the PXR operates with the SV0 affected by the SV limiter.

[Setting example] Setting the upper limiter to 100°C

| Display | Operating procedure |
|---------------------|--|
| 150 150 P-n 1 | 1. Press and hold the SEL key for five seconds. P-n { will be displayed on the PV display. |
| 55-X 400 | 2. Press the key to display 5 |
| - <u>700</u> | 3. Press the SEL key once. The current setting (400) flashes on the SV display. |
| 55-H -)00]- | 4. Press the or keys to display (III). |
| 5ū-X 100 | 5. Press the SEL key once. 100 will stop flashing and will be registered for 5 - H. After that, the upper limit of the SV will be 100°C. |
| 150 100 | 6. If you want to display the operation status, press and hold the SEL key for two seconds. |

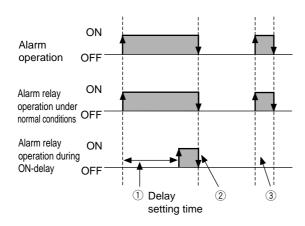
The time of ON-delay alarm or timer function

(Setting range: 0 to 9999 seconds)

[Description]

ON-delay alarm

- With this function, the alarm relay is closed after the predetermined delay time. (See operation ① shown in the figure below.)
- In case the cause of the alarm is solved within the delay time, the alarm relay is not closed. (See operation ③ shown in the figure below.)
- The alarm relay is opened regardless of this parameter. (See operation ② shown in the figure below.)

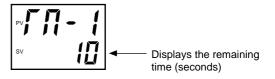


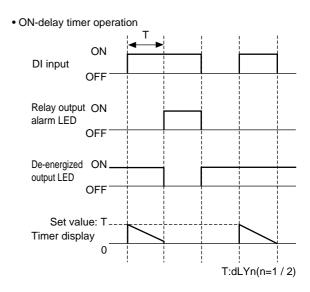
- In case the alarm is set to OFF during standby, the ONdelay operation performs again when returning to RUN.
- When the delay time is changed during ON-delay operation, the alarm is activated in the changed delay time.

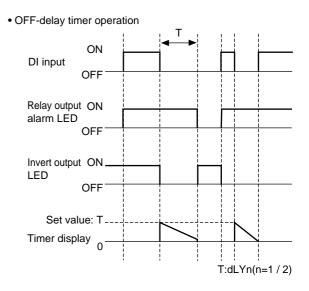
Timer function

- When the ON-delay timer is selected (ALMn = 32), the relay is closed in the set time after DI input is set to ON. While the DI input stays OFF, the timer cannot be activated.
- When the OFF-delay timer is selected (ALMn = 33), the timer cannot be activated while the DI input is set to ON. The relay is closed in the set time after DI input is set to OFF.
- When the ON/OFF-delay timer is selected (ALMn = 34), the timer is activated while the DI input stays either ON or OFF.

- The timer display function shows the remaining time of timers 1, 2 and 3.
- The set time is counted down while the ON or OFF timer is activated.
- While the ON timer is activated, the alarm relay is closed when the remaining time is 0. While the OFF timer is activated, the alarm relay is opened when the remaining time is 0.







[Setting example] Setting the delay time for ON-delay alarm to 30 seconds —

| Display | Operating procedure | | |
|-------------------------|--|--|--|
| 1499 1500 P-n 1 | 1. Press and hold the SEL key for five seconds. P-n { will be displayed on the PV display. | | |
| dL Y [| 2. Press the key to display dly!. | | |
| - <u>'</u> ût 97.7.1 | 3. Press the SEL key once. The current setting ([]) flashes on the SV display. | | |
| -3tt | 4. Press the or keys to display ∃₽. | | |
| 30 dl 3 l | 5. Press the <u>SEL</u> key once. 30 will stop flashing and will be registered for dLY!. After that, the controller will operate with the ON-delay alarm being 30 seconds. | | |
| 1499 1500 | 6. If you want to display the operation status, press and hold the SEL key for two seconds. | | |

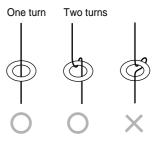
Displaying current detector input (Display only) (Option)

HB (Set value of heater break alarm) (Setting range: 0.0 to 50.0 A) (Option)

[Description] -

- When **Hb** is set to 0.0, the HB alarm is turned OFF.
- The point at which the alarm is activated can be set in the parameter of Hb.
- There are two types of the current transformers (CT) available: CTL-6-SF type for 1 A to 30 A and CTL-12-S36-8F type for 20 A to 50 A. Select the suitable type to the current value of the heater you use.
- How to set the point at which the alarm is actevated:
 - Set the output of the PXR to ON continuously to provide the current to the heater.
 - You can monitor the current value of the heater in the parameter of $\Gamma\Gamma$. Set the value that is 70 to 80 % of the monitored current value as the final set value.
 - When the number of heaters is "n" (more than two), set the middle value between the current of "n" heaters and the current of ("n"-1) heaters.
- When the thyristor (SCR) phase control system is used to control the heater, the parameters of [] and Hb cannot be used.

- In case detection of an error becomes difficult due to insufficient heater capacity, pass the wire through the CT twice to double the apparent current. This will improve the sensitivity of the CT. (In this case, set the value that is twice as much as the original value.)
- When winding the wire around the CT several times, be sure to wind in the same direction.

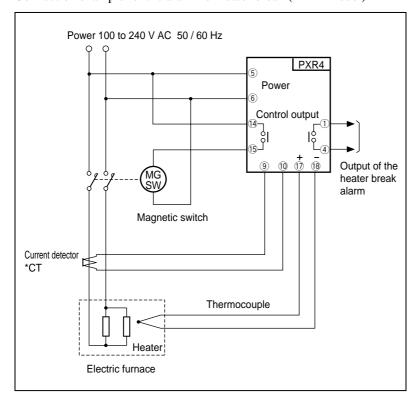


[Note]

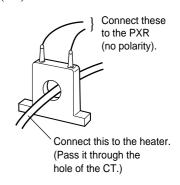
To detect heater current, control output 1 must be kept on for 0.5 second or longer.

Related parameter: **[**[(page 37)

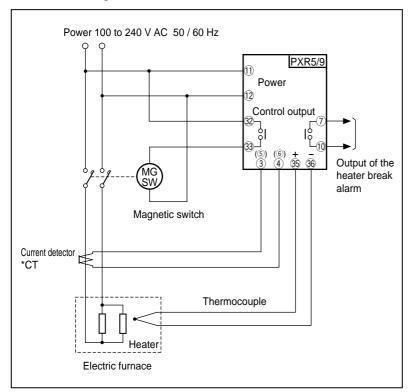
• Connection example for the alarm for heater break (PXR4 model)



• How to connect the current transformer (CT) for heater break:



• Connection example for the alarm for heater break (PXR5/9 model)



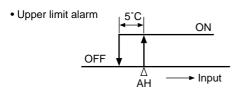
[Setting example] Changing the detecting current of heater break from 8.0 A to 9.0A —

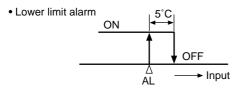
| Display | Operating procedure | | |
|-----------------------|---|--|--|
| 1499 1500 P-n 1 | 1. Press and hold the <u>SEL</u> key for five seconds. P-n ! will be displayed on the PV display. | | |
| НЬ 80 | 2. Press the key to display #b. | | |
| НЬ -80 | 3. Press the SEL key once. The current setting (BD) flashes on the SV display. | | |
| -90) | 4. Press the or keys to display 90. | | |
| НЬ 90 | 5. Press the <u>SEL</u> key once. 911 will stop flashing and will be registered for Hb . After that, the controller will operate with detecting current of heater break being 9.0A | | |
| 1499 1500 | 6. If you want to display the operation status, press and hold the SEL key for two seconds. | | |

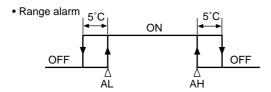
Hysteresis of alarm 1, 2 and 3 (Setting range: 0 to 50% FS) (Option)

[Description] -

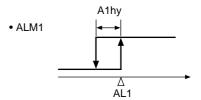
- The alarm is detected in the two-position operation (ON/OFF). The hysteresis means the difference between the input at ON and the input at OFF. For example, the hysteresis of 5°C means that the range between ON and OFF is 5°C.
- As to the decimal point position, the setting at P dP is respected.

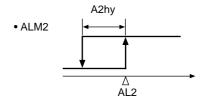


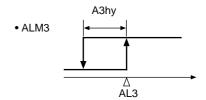




• Hysteresis can be set for each alarm.







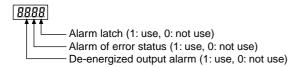
[Setting example] Changing the hysteresis of alarm 2 from 1°C to 3°C -

| Display | Operating procedure | | |
|-----------------------|--|--|--|
| 1499 1500 P-n 1 | 1. Press and hold the SEL key for five seconds. P-n ! will be displayed on the PV display. | | |
| ASYA! | 2.Press the we key to display 用されら | | |
| 82h4 -] - | 3. Press the SEL key once. The current setting (!) flashes on the SV. | | |
| R254 31 | 4. Press the or keys to display 3. | | |
| 8243 3 | 5. Press the SEL key once. 3 will stop flashing and will be registered for R2hy. After that, the controller will operate with the hysteresis of alarm 2 being 3°C. | | |
| 1499 1500 | 6. If you want to display the operation status, press and hold the SEL key for two seconds. | | |

RIP, **RIP**, Options of alarm 1, 2 and 3 (Setting range: 000 to 111) (Option)

[Description]

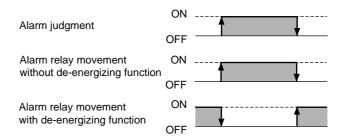
- These parameters are used to switch ON/OFF of the alarm latch, the error satus alarm, and the de-energized output alarm functions for each of Alarm 1, 2 and 3.
- Each function is set to ON by setting the following digit to "1":



- The alarm latch is the function to keep the alarm ON, once the alarm judgment shows the alarm ON status. To cancel the alarm latch, follow the instructions below.
 - Power off the PXR, and then on.
 - Set the alarm latch to OFF.
 - Cancel the alarm latch at the alarm latch cancelling parameter.
 - Cancel the alarm latch by DI input.
 - Cancel the alarm latch via communication.
- The alarm of error status is activated, when the problems in the table below occur. When using this error status alarm function, set the alarm types (ALM1, 2 or 3) to "0".

| Display | Causes | | |
|---------|---|--|--|
| טטטט | A break in the thermocouple sensor A break in the resistance bulb sensor (RTD) (A) The PV reading value exceeds the P-SU by 5%FS or more. | | |
| LLLL | A break in the resistance bulb sensor (B) or (C) The resistance bulb sensor (A-B) or (A-C) is short-circuited. The PV reading value is below the P-SL by 5%FS or more. A break or a short-circuit in the voltage input line. | | |

• The de-energized output alarm function is used for energizing or de-energizing the alarm relay to be closed. While this function is set to ON, when the alarm judgment shows the ON status, the relay is opened, and when the alarm judgment shows the OFF status, the relay is closed.



[Note]

- The ON-delay, the alarm latch, and the de-energized output functions can be activated for the error status alarm.
- The alarm lamps (AL1, AL2, AL3) goes on and off according to the alarm judgment regardless of the de-energized output settings.

[Setting example] Setting the error status alarm function for Alarm 2 to ON -

| Display | Operating procedure | | |
|-----------------------|---|--|--|
| 1499 1500 P-n 1 | 1. Press and hold the SEL key for five seconds. P-n ! will be displayed on the PV display. | | |
| R2oP 000 | 2. Press the key to display R20P. | | |
| 82aP 300 | 3. Press the SEL key once. The current setting ([] []) flashes on the SV display. | | |
| 72aP -13 IU | 4. Press the or keys to display [] []. | | |
| R2oP 0 (0 | 5. Press the <u>SEL</u> key once. !! will stop flashing and will be registered for R20P . After that, the controller will operate with the error status alarm function for Alarm 2 being ON. | | |
| 1499 1500 | 6. If you want to display the operation status, press and hold the SEL key for two seconds. | | |

PL[], PH[] Upper and lower limits for control output 1 (Setting range: -3.0 to 103.0%)

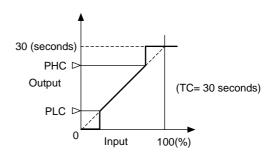
Upper and lower limits for control output 2 (Setting range: -3.0 to 103.0%) (Option)

[Description] -

• These parameters set the limit value of output.

| | Upper limit | Lower limit |
|------|-------------|-------------|
| OUT1 | PHC1 | PLC1 |
| OUT2 | PHC2 | PLC2 |

- How the output is limited (maintained within the limit or breaks the limit) is set in the parameter of P[U].
- When flammability is controlled by turning the gas on and off, this function can avoid flashing.



Related parameters: **[**[(page 37)

P[] (page 63)

(Minimum ON pulse width [seconds]) =
$$PLL I \times \frac{100}{TC}$$

(Minimum OFF pulse width [seconds]) = $(100 - PHC I) \times \frac{100}{TC}$

「[: Cycle time

[Setting example] Changing the lower pulse width limit from 20.0% to 10.0%

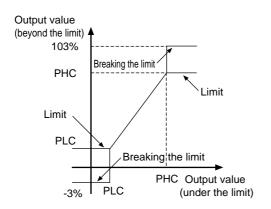
| Display | Operating procedure | |
|-----------------------|---|--|
| 1499 1500 P-n 1 | 1. Press and hold the SEL key for five seconds. P-n { will be displayed on the PV display. | |
| PL[1 200 | 2. Press the key to display PL[]. | |
| PLC (| 3. Press the SEL key once. The current setting (200) flashes on the SV display. | |
| PLE (-,00 | 4. Press the or keys to display III . | |
| PLC 1 | 5. Press the SEL key once. (CC) will stop flashing and will be registered for PL[1. After that, the controller will operate with the output lower limit being 10%. | |
| 1499 1500 | 6. If you want to display the operation status, press and hold the SEL key for two seconds. | |



Output limit types (Setting range: 0 to 15)

[Description] -

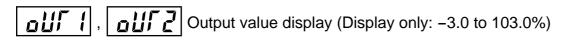
• This parameter sets whether or not to maintain the value within the limit when the output value increases up to the limit set value.



| | Output 1 | | Output 2 | |
|------|-------------|-------------|-------------|-------------|
| PCUT | Upper limit | Lower limit | Upper limit | Lower limit |
| 0 | 103% | -3% | 103% | -3% |
| 1 | 103% | Limit | 103% | -3% |
| 2 | Limit | -3% | 103% | -3% |
| 3 | Limit | Limit | 103% | -3% |
| 4 | 103% | -3% | 103% | Limit |
| 5 | 103% | Limit | 103% | Limit |
| 6 | Limit | -3% | 103% | Limit |
| 7 | Limit | Limit | 103% | Limit |
| 8 | 103% | -3% | Limit | -3% |
| 9 | 103% | Limit | Limit | -3% |
| 10 | Limit | -3% | Limit | -3% |
| 11 | Limit | Limit | Limit | -3% |
| 12 | 103% | -3% | Limit | Limit |
| 13 | 103% | Limit | Limit | Limit |
| 14 | Limit | -3% | Limit | Limit |
| 15 | Limit | Limit | Limit | Limit |

[Setting example] Selecting the operation that outputs 1 and 2 are maintained within the upper and lower limits ——

| Display | Operating procedure | | |
|-----------------------|--|--|--|
| 1499 1500 P-n 1 | 1. Press and hold the SEL key for five seconds. P-n! will be displayed on the PV display. | | |
| PEUF | 2. Press the key to display P[U]. | | |
| יים בער בער | 3. Press the SEL key once. The current setting ([]) flashes on the SV display. | | |
| PEUF -)5: | 4. Press the or keys to display 15. | | |
| PEUT (5 | 5. Press the SEL key once. 15 will stop flashing and will be registered for PEUF . After that, the controller will operate with outputs 1 and 2 maintained within the upper and lower limits. | | |
| 1499 1500 | 6. If you want to display the operation status, press and hold the SEL key for two seconds. | | |



[Description] -

• These parameters display the output values of outputs 1 and 2 in the unit of %. (Since the values are calculated with the software, they may have some error comparing to the actual output.)

[Setting example] Confirming the output value (the calculated value) of control output 1 ———

| Display | Operating procedure |
|-----------------------|---|
| 1499 1500 P-n 1 | 1. Press and hold the SEL key for five seconds. P-n ! will be displayed on the PV display. |
| 0UT 1 885 | 2. Press the key to display off!. The output value will appear in the SV display. |
| 1499 1500 | 3. If you want to display the operation status, press and hold the SEL key for two seconds. |



RCJ (Cold junction compensation) (Setting range: ON/OFF)

[Description] -

• This parameter sets whether or not to perform the RCJ (Cold junction compensation) for the thermocouple input. Use the factory default setting (ON: performs the RCJ) under normal conditions.

ON: Performs the RCJ (Cold junction compensation).

OFF: Does not perform the RCJ (Cold junction compensation).

• Set this parameter to OFF under the conditions that the RCJ is not needed, such as when the RCJ is performed outside of the PXR or when the temperature deviations are recorded.

[Setting example] Changing the RCJ (Cold junction compensation) from ON to OFF -

| Display | Operating procedure | | |
|--|---|--|--|
| 1499 1500 P-n 1 | 1. Press and hold the SEL key for five seconds. P-n ! will be displayed on the PV display. | | |
| r[J | 2. Press the wey to display r.[.]. | | |
| - <u>`</u> - <u>`</u> - <u>`</u> - <u>`</u> - <u>`</u> - | 3. Press the SEL key once. The current setting (an) flashes on the SV display. | | |
| ر [با -۵۴۴ | 4. Press the or keys to display of . | | |
| r[d oFF | 5. Press the SEL key once. GFF will stop flashing and will be registered for FLU . After that, the controller will operate with the RCJ (Cold junction compensation) being GFF . | | |
| 1250 1500 | 6. If you want to display the operation status, press and hold the SEL key for two seconds. | | |

Adjusting the PV (Measured value) display (0%) (Setting range: -50 to 50% FS)

Adjusting the PV (Measured value) display (100%) (Setting range: -50 to 50% FS)

[Description]

- The user-definable functions are independent of the adjustment values of the PXR. Setting the parameters of Rauli and Rdd5 to II can return to the factory default settings.
- 1. Prepare the following devices before adjustment by using these parameters.
 - · DC voltage standard generator

1 to 5V (for voltage input)

0 to 100 mV (for thermocouple input)

· Decade resistance box

100.0 to 400.0 Ω (for resistance bulb input)

- **2.**Set the parameter of r [] to OFF.
- **3.**Apply a voltage that is equivalent of 0%. If there is an error large enough to impair its accuracy, set the parameter of R_{α} (See the right example to set RdJO.)
- **4.** Apply a voltage that is equivalent of 100%. If there is an error large enough to impair its accuracy, set

the parameter of Rd d 5. (See the right example to set RdJ5.)

5. Return the parameter of r[] to ON.

[Operating example for input range of 0°C to 400°C]

Reading at input of 0°C: -1°C Reading at input of 400°C: 402°C

Set the parameter of #dull to "1". Set the parameter of \mathbb{A}_{1} to "-2".

Therefore:

Reading at input of 0°C: 0°C Reading at input of 400°C: 400°C

[Adjustment example for input range of 0 to 400°C]

| Before adjustment | Adjustment value | After adjustment |
|----------------------------------|------------------|----------------------------------|
| Display at input of 0°C: -1°C | <i>RdJ0</i> :1 | Display at input of 0°C: 0°C |
| Display at input of 400°C: 402°C | RdJ5:-2 | Display at input of 400°C: 400°C |

Setting the parameters of Rauli and Rauli to "0" returns to the factory default settings.

[Setting example] Setting the zero adjustment to "+1°C"

| Diamlass | On and the second line |
|-----------------------|---|
| Display | Operating procedure |
| 1499 1500 P-n 1 | 1. Press and hold the SEL key for five seconds. P-n { will be displayed on the PV display. |
| RaJO | 2. Press the key to display #dull . |
| - <u>-</u> 0- | 3. Press the SEL key once. The current setting ([]) flashes on the SV display. |
| 7.1 1 | 4. Press the or keys to display !. |
| 1 8440 | 5. Press the <u>SEL</u> key once. I will stop flashing and will be registered for Rdull . After that, the controller will operate with the zero adjustment being +1°C. |
| 1499 1500 | 6. If you want to display the operation status, press and hold the SEL key for two seconds. |

DI operation (Setting range: 0 to 12) (Option)

[Description] -

• Select each DI function with $d\vec{L} - l$ and $d\vec{L} - \vec{l}$ (DI setting parameter) and set the DI to ON to activate the functions.

Setting range: 0 to 12

n = No function

t = Switches the SV.

∠ = Control RUN/Standby

3 = Starts the auto tuning (standard).

Y = Starts the auto tuning (low PV).

5 = Cancels latching for all alarms.

 $\mathbf{E} =$ Cancels latching for alarm 1.

7 = Cancels latching for alarm 2.

 \mathbf{g} = Cancels latching for alarm 3.

9 = Activates ALM 1 relay timer.

= Activates ALM 2 relay timer.

= Activates ALM 3 relay timer.

= Ramp-soak operation RUN/RESET

Switching the SV (DI function 1)

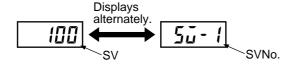
• This function switches the SV.

(Exp.) In case of switching SV 4 points

DI set parameter, DI and type of SV to be switched and selected

| dī - 1 | d[-] | DI2 | OFF | DI2 | ON |
|-----------|-----------|---------|--------|---------|--------|
| Set value | Set value | DI1 OFF | DI1 ON | DI1 OFF | DI1 ON |
| 1 | 1 | 5ŭ | 5ŭ- 1 | 50-2 | 50-3 |

- 5<u>u</u> I of the ramp-soak target SV is used to set the SV 1.
- The SV cannot be changed on the SV display screen while 5u - l is selected.
- While switching the SV, the SV and the SV No. appear alternately. (SV: 2 seconds, SV No.: 1 second)
 However, the SV No. is not displayed during the rampsoak operation.



Ramp-soak operation RUN/RESET (DI function 12)

 The ramp-soak operation is switched between RUN/ RESET by DI.

DI ON edge ↑: RUN

DI OFF edge ↓: RESET

[Note]

RUN and RESET are switched by ON and OFF edge of DI.

- The ramp-soak operation can be also switched between RUN/RESET manually.
- The ramp-soak execute types that are set in the parameter of **P**[n] operate.
- The table below shows the operations when the DI changes during ramp-soak operation.

| Ramp-soak | DI | |
|------------------|-----------|-----------|
| operation status | ON edge | OFF edge |
| RUN | No change | RESET |
| RESET | RUN | No change |
| HOLD | RUN | RESET |
| END | No change | RESET |

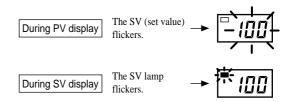
• When the settings are set manually, via communication, and DI, the settings that are set later are valid.

Switching control RUN/Standby (DI function 2)

· RUN and Standby mode is switched by DI

DI ON : Standby DI OFF: RUN

• When the control is in standby state,



 The control can also be switched between RUN/ Standby manually.

Select ON or OFF in the parameter for 5,7 by (Setting standby).

5/ b ያ setting screen (the first block)

Display during OFF: Control RUN mode

Display during ON: Control Standby mode

 The table below shows the relationship between the RUN and Standby mode switched with a manual operation, DI 1, and ramp-soak operation.

| | Standby status of ramp-soak operation | | | |
|--------|---------------------------------------|---------|---------|---------|
| DI | OFF | | ON | |
| וט | Manual setting | | | |
| | OFF | ON | OFF | ON |
| DI OFF | RUN | Standby | Standby | Standby |
| DI ON | Standby | Standby | Standby | Standby |

Starting the auto-tuning (DI functions 3, 4)

• These functions can switch the start/stop of the autotuning.

| DI function | DI ON edge | DI OFF edge |
|---------------|------------|-------------|
| AT (Standard) | AT start | AT concel |
| AT (Low PV) | Arstan | AT cancel |

Cancel the alarm latch (DI functions 5 to 8)

• These functions can cancel the alarm latch while alarms are latched by setting the alarm latch function to ON.

| Set value of di - l or di - l | DI ON | DI OFF |
|-------------------------------|----------------------|-----------------|
| F | Cancels the latching | |
| 5 | for alarms 1 and 2 | |
| 6 | Cancels the | |
| б | latching for alarm 1 | Keeps the alarm |
| 7 | Cancels the | latching |
| / | latching for alarm 2 | latoring |
| 0 | Cancels the | |
| 0 | latching for alarm 3 | |

Timer operation (DI functions 9 to 11)

• The DI can set the ON/OFF of timer while codes 32 to 34 are set in "Setting alarm types" (page 46). For the operation, see page 46.

[Setting example] Changing the SV (Front SV) to SV1 —

| Display | Operating procedure |
|---------------------------|--|
| [1499] PV indication | 1. Press and hold the SEL key for five seconds. P-n! will be displayed. |
| <u>dī-1</u> | 2. Press the key to display di-1. |
| | 3. Press the <u>SEL</u> key once. The current setting (1) will be displayed. |
| | 4. Press the or keys to flicker and to display \(\begin{align*}\). |
| dī-1 | 5. Press the \overline{SEL} key once. $d\overline{L} = 1$ will be displayed and 1 will be registered for $d\overline{L} = 1$. (Repeat the procedure from 3 to 5 to check the set value.) |
| | 6. Short-circuit the Di1 terminals. The SV will be changed from the front SV to SV1. |
| 2500 SV indication | 7. If you want to display the operation status, press and hold the SEL key for two seconds. The SV value and SV No. will appear alternately. The switched SV or 54 · 1 will be displayed alternately on the display area. |
| PV indication | If unoperated state continues, the PV will be displayed. |

Station No. for communication (Setting range: 0 to 255)

[Description] —

- Do not set the same number as other Micro-controllers.
- See Communication function instruction manual for details.

[Setting example] Setting the station No. to "123" ————

| Display | Operating procedure |
|-----------------------|--|
| 1499 1500 P-n 1 | 1. Press and hold the SEL key for five seconds. P-n ! will be displayed on the PV display. |
| 5/ no | 2. Press the key to display 55 no. |
| 51 na | 3. Press the SEL key once. The current setting (!) flashes on the SV display. |
| 51.np | 4. Press the or keys to display 123. |
| 57 no 123 | 5. Press the SEL key once. 123 will stop flashing and will be registered for 5 [no. After that, the controller will operate with the station number being 123. |
| 1499 1500 | 6. If you want to display the operation status, press and hold the SEL key for two seconds. |

[Note]

- In the case of Modbus (RTU) communication specifications, communication is prohibited if the station No. is set to 0.
- In the case of Z-ASCII communication specifications, communication is allowed even if the station No. is set to 0.



Parity for communication (Setting range: 0 to 2)

[Description] —

• This parameter sets the parity for communications.

The baud rate is fixed at 9600bps.

🛚 : Odd parity : Even parity

∠ : No parity

[Setting example] Setting the even parity -

| Display | Operating procedure |
|-----------------------|---|
| 1499 1500 P-n 1 | 1. Press and hold the SEL key for five seconds. P-n ! will be displayed on the PV display. |
| [<u>[</u> 0] | 2. Press the key to display $\mathcal{L}_{\alpha}\Pi$. |
| - <u>`</u> 0}- | 3. Press the SEL key once. The current setting ([]) flashes on the SV display. |
| | 4. Press the or keys to display t. |
| [Coff | 5. Press the <u>SEL</u> key once. ! will stop flashing and will be registered for <u>Eafl</u> . However, it does not switch to the even parity at this point. |
| 1499 1500 | 6. Power off the PXR, and then on. The even parity is set now. |

PEaL

Communication protocol setting (Setting range: 0 to 1) (Option)

[Description] -

• This parameter is used to switch communication protocols.

| Set value | Output type |
|-----------|-----------------------|
| 1 | Modbus (RTU) protocol |
| 0 | Z-ASCII protocol |

- * See the following communication specifications for details of each protocol.
 - Instruction manual for Micro Controller X communication functions (RS485 MODBUS).......INP-TN512642-E
 - Instruction manual for Micro Controller X communication functions (RS485 Z-ASCII)INP-TN512644-E

Related parameters: $5 \Gamma_{\Omega\Omega}$ (page 70) $\Gamma_{\Omega}\Pi$ (page 71)

[Setting example] Changing to Z-ASCII protocol -

| Display | Operating procedure |
|-----------------------|--|
| 1499 1500 P-n 1 | 1. Press and hold the SEL key for 5 seconds. P-n { will be displayed in the PV display section. |
| PEal | 2. Press the key to display P[a]. |
| PE oL | 3. Press the SEL key once. The current set value (1) in the SV display section flickers. |
| P[al -, 0] - | 4. Press the and keys to display []. |
| PC oL | 5. Press the <u>SEL</u> key once. Flickering stops and <u>n</u> will be registered in <u>PLaL</u> . The operation is then performed using Z-ASCII protocol. |
| 1250 1500 | 6. To display the operation status, press and hold the SEL key for 2 seconds. |

Re-transmission output type setting (Setting range: 0 to 3) (Option)

[Description] -

• This parameter is used to set the retransmission output type.

The means of the set values are as shown below.

| Set value | Output type |
|-----------|-------------|
| 0 | PV |
| 1 | SV |
| 2 | MV |
| 3 | DV |

Related parameters: \mathcal{H}_{Ω} - \mathcal{L} (page 74) \mathcal{H}_{Ω} - \mathcal{H} (page 74)

[Setting example] Changing the retransmission output type from the process value (PV) to the set value (SV)

| Display | Operating procedure | | |
|-------------------------|---|--|--|
| 25 PV indication | 1. Press and hold the SEL key for 5 seconds. | | |
| P-n 1 | P-n ! will be displayed. | | |
| Ro-1 | 2. Press the \searrow key to display $\Re_{\alpha} - \Gamma$. | | |
| | 3. Press the SEL key once. | | |
| | The current setting (0 : PV retransmission) will be displayed. | | |
| | 4. Press the or key to flicker and to display ! (SV retransmission). | | |
| Ro-F | 5. Press the SEL key once. Ro-Twill be displayed and 1 (SV retransmission) will be registred for the retransmission output type. After that, the controller will operate with the retransmission output being SV. | | |
| | (Repeat the procedure from 3 to 5 to check the set value.) | | |
| 25 SV indication | 6. If you want to display the operation status, press and hold the SEL key for two seconds. The SV will be displayed on the display area. | | |
| 25 PV indication | If unoperated state continues, the PV will be displayed. | | |

Ro-L

Re-transmission base scale (Setting range: -100.0 to 100.0%) (Option)

Ro-X

Re-transmission span scale (Setting range: -100.0 to 100.0%) (Option)

[Description] -

• The retransmission base scale and span scale can be set as shown below. Unit for the setting is %.

| Output type | Description of percentage |
|-------------|---------------------------------|
| PV/SV/DV | Percentage of input measurement |
| | range (Note 1) |
| MV | Output value |

Note 1: Calculate the set value by using the following formula (refer also to the setting example shown below).

Set value (%) =
$$(A \div B) \times 100$$
 [%]

A = Temperature to be set - Set value of parameter "P-SL"

B = Set value of parameter "P-SU" – Set value of "P-SL"

- When the value of retransmission output (example: SV) becomes equal to the set value of Ao-L, the retransmission output becomes 0% (output).
- When the value of retransmission output (example: PV) becomes equal to the set value of Ao-H, the retransmission output becomes 100% (output).

Related parameters: 🚜 🗗 - 🞵 (page 73)

[Note]

• Be sure to always set \mathcal{R}_{Ω} - \mathcal{L} smaller than \mathcal{R}_{Ω} - \mathcal{H} .

[Setting example] At K thermocouple input of 0 to 400°C, make the setting so that the PV (value of retransmission output type) becomes 0% at 100°C, and 100% at 300°C.

Since the measurement range is 0 to 400° C, P - SL = 0 (lower limit value of measurement range), and P - SU = 400 (upper limit value of measurement range). So, from the formula shown above,

 $A = (100^{\circ}C - 0) \text{ or } (300^{\circ}C - 0), B = 400 - 0 = 400$

- 1) Setting Ao-L : What position is 100° C in the temperature range from 0 to 400° C ? = 25% (= $(100-0) \div 400 \times 100$ [%]) \rightarrow Ao-L = 25.0 (%)
- 2) Setting Ao-H: What position is 300° C in the temperature range from 0 to 400° C? = 75% (= $(300 0) \div 400 \times 100$ [%]) \rightarrow Ao-H = 75.0 (%)

| Display | Operating procedure |
|-------------------------|---|
| P-n (| 1. Press and hold the SEL for five seconds. P-n ! will be displayed. |
| Ro-L | 2. Press the \searrow key to display R_{a} - L . |
| 0.0 | 3. Press the <u>SEL</u> key once. The current setting value will be displayed. |
| <u> </u> | 4. Press the \bigcirc or \bigcirc key to flicker and to display 250 . |
| Ro-L | 5. Press the SEL key once. Ro - L will be displayed and 250 will be registered for the retransmission base scale. (Repeat the procedure from 3 to 5 to check the set value.) |
| Ro-H | 6. Press the key to display $R_{\mathcal{O}}$ - \mathcal{H} . |
| 100.0 | 7 . Press the <u>SEL</u> key once. The current setting value will be displayed. |
| <u> </u> | 8. Press the \bigcirc or \bigcirc key to flicker and to display 750. |
| Ro-H | 9. Press the $\overline{\mathit{SEL}}$ key once. $\mathcal{H}_{\mathcal{Q}}$ - \mathcal{H} will be displayed and $75\mathcal{Q}$ will be registered for the retransmission span scale. |
| | (Repeat the procedure from 7 to 9 to check the set value.) |
| 25 SV indication | 10. If you want to display the operation status, press and hold the SEL key for two seconds. The SV will be displayed on the display area. |
| 25 PV indication | If unoperated state continues, the PV will be displayed. |

Remote SV input (0%) adjustment (Setting range: -50 to 50% FS) (Option)

FERS Remote SV input (100%) adjustment (Setting range: -50 to 50% FS)

[Description] —

- * These parameters are used to correct the deviation of remote SV input.

 By setting 0 to the parameters, the status at the time of delivery from the factory can be restored.
- 1. To correct the deviation from zero point (0% input side)
 - (1) Enter the value equivalent to 0% to remote SV.
 - (2) Check that $r = 5\bar{u}$ is displayed, and then check the deviation of SV value on the 0% side.
 - (3) Enter in $r \notin \Pi \Pi$ the value to correct the deviation observed in (2).
 - (4) Check on the $r \int \bar{u}$ display that the input has been corrected.
- 2. To correct the deviation of span point (on 100% input side)
 - (1) Enter the value equivalent to 100% to remote SV.
 - (2) Check that $r = 5\bar{u}$ is displayed, and then check the deviation of SV value on the 100% side.
 - (3) Enter in $r \notin \Pi S$ the value to correct the deviation observed in (2).
 - (4) Check on the $r 5 \bar{u}$ display that the input has been corrected.

Related parameters: [find (page 17) r-dF (page 76) r 5ū (page 77)

[Setting example] Setting zero adjustment +1°C ————

| Display | Operating procedure |
|-----------------------|---|
| 1499 1500 P-~ 1 | 1. Press and hold the SEL key for 5 seconds. P-n ! will be displayed in the PV display section. |
| rENO O | 2. Press the we key to display r E∏Ū. |
| - E (10) 0)- | 3. Press the SEL key once. The current set value (1) in the SV section flickers. |
| - E \(\bar{U} \) | 4. Press the and keys to display !. |
| r E N O | 5. Press the \boxed{SEL} key once. Flickering stops and $r \in \Pi \Pi = 1^{\circ}C$ is registered. The operation is then performed at zero adjustment $+1^{\circ}C$. |
| 1499 1500 | 6. To display the operation status, press and hold the SEL key for 2 seconds. |



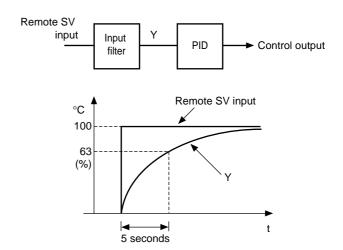
r - dF | Remote SV input filter constant (Setting range: 0.0 to 900.0 seconds)

[Description] -

• This parameter is used to make the input signal fluctuation range smaller (filtering function). Suppose that the input filter constant is set to 5 seconds. If the input is suddenly changed from 0 to 100%, the PV display gradually changes as shown in the figure on the right, and it takes 5 seconds to change from 0 to 63.2%.



• The value is set to 0.0 at the time of delivery (filter OFF). Do not change the value unless required.



[Setting example] Changing the filter constant from 0.0 (filter OFF) to 5.0 (5 seconds)

| Display | Operating procedure |
|-----------------------|--|
| 1499 1500 P-n 1 | 1. Press and hold the <u>SEL</u> key for 5 seconds. P-n { will be displayed in the PV display section. |
| r - dF 00 | 2. Press the \searrow key to display $r - dF$. |
| r - dF -,00}- | 3. Press the <u>SEL</u> key once. The current set value (<u>DD</u>) in the SV display section flickers. |
| r - dF -50- | 4. Press the and keys to display 5 |
| r - dF 50 | 5. The operation will then be performed with the filter constant of 5.0 seconds. |
| 1499 1500 | 6. To display the operation status, press and hold the SEL key for 2 seconds. |



Remote SV input value display (Display only: -1999 to 9999) (Option)

[Description] -

• These parameters are used to correct the deviation of remote SV input.

(The value obtained by calculations for remote SV input filter and remote SV input adjustment is displayed as $r5\overline{u}$ display value.)

[Setting example] Checking the remote SV input value -

| Display | Operating procedure |
|-----------------------|--|
| 1499 1500 P-n 1 | 1. Press and hold the SEL key for 5 seconds. P-n ! will be displayed in the PV display section. |
| r 5ú 298 | 2. Press the key to display $r 5 \bar{u}$. The remote SV input value is displayed in the SV display section. |
| (499 (500 | 3. To display the operation status, press and hold the SEL key for 2 seconds. |



[Description] —

- This parameter skips the parameter display by items.
- This parameter is used not to display the items that are not used, or not to change the settings mistakenly.
- "Parameter mask DSP" in "2-1 Parameter list" (pages 7 to 11) shows which parameter is skipped by setting d5P 1 to d5P9 and dP = 10 to dP = 13.
- Set the total value of the item codes that you want to skip.

[Setting example 1] Skipping "I" and "d"

Setting "4+8=12" according to the code table of dSP3 -

| Display | Operating procedure |
|-----------------------|--|
| 1499 1500 P-n 1 | 1. Press and hold the SEL key for five seconds. P-n! will be displayed on the PV display. |
| d5P3 | 2. Press the key to display d5P3. |
| 45P3 -,0+ | 3. Press the SEL key once. The current setting ([]) flashes on the SV display. |
| d5P3 -)23 | 4. Press the or week keys to display ع. |
| d5P3 (2 | 5. Press the <u>SEL</u> key once. 12 will stop flashing and will be registered for <u>d</u> 5P3. After that, the parameters of <u>r</u> and <u>d</u> will be skipped, and will not be displayed. |
| 1499 1500 | 6. If you want to display the operation status, press and hold the SEL key for two seconds. |

[Setting example 2] Extinguishing the PV display

Reducing 64 from parameter dP13 —

| Operating procedure |
|--|
| 1 Display parameter dP 13. |
| 2. Check a currently displayed value of $dP / 3$ and reduce 64 from the value. (Example: When a value of $dP / 3$ is 127, 127-64=63). |
| 3. Re-set the result of calculation obtained from Step 2 to dP 13. (Example: Set 63 to dP 13). |

[Setting example 3] Displaying the PV display (factory default)

| Adding 64 to a value of parameter dP13 ———————————————————————————————————— |
|--|
| Operating procedure |
| 1. Display parameter dP 13. |
| 2. Check a currently displayed value of $dP / 3$ and add 64 to the value. (Example: When a value of $dP / 3$ is 63, 63+64=127). |
| 3. Re-set the result of calculation obtained from Step 2 to dP 13. (Example: Set 127 to dP 13). |

3 Troubleshooting

This section explains the judgments and remedies for problems.

| Symptoms | Possible causes | Remedies | Reference pages |
|---|--|---|-----------------|
| 1. The display has shown | 1) The setting of $P - n Z$ is not correct for the input signals of sensors or others. | Set the parameter of P-n2 correctly. | Page 39 |
| | ② The polarity of the sensor does not match that of the PXR. | Correct the polarity of the sensor and the PXR. | Page 57 |
| | (3) Input terminals are short-circuited in thermocouple B or R. (P-n2 = 4, 5) | Set the parameter of $P - n Z$ to 3, and check if the temperature around an ordinary temperature is displayed. (Thermocouples B and R have a large error around ordinary temperatures. However, this is not a fault.) | Page 39 |
| | (4) The input signals of sensors or others do not match those of the controller you use. | Ask to make adaptations on your model. Or replace your model with a new one. | - |
| | (5) The connecting cables for the sensor are loose.(6) A break or short-circuit occurred in the sensor. | Tighten the connecting cables. Replace the sensor with a new one. Or remove the short-circuit. | - |
| | ① The sensor or other input devices that are connected to the PXR have problems. | Replace the sensor or other input devices with new ones. | - |
| | 8 The set value of the parameter of $P - 5L$ is larger than the value of $P - 5U$. | Set the parameters again so that the value of $P - 5L$ is smaller than the value of $P - 5L$. | Page 40 |
| | (9) The measured value is too large or too small. | Set the parameters again so that the difference of the set values of P - 51 and P - 511 is made larger. | |
| 2. Frr has been displayed. | 1) The value of P - 5 !! is set to 3277°C or more for thermocouple and resistance bulb input. | Set the parameters of $P - 5L$ and $P - 5U$ again according to the input range table. | Page 40 |
| | ② The measured range ($P - 5U$ to $P - 5L$) is set to 10000 or more for voltage and current input. | Set the parameters of $P - 5L$ and $P - 5U$ again so that the measured range is 9999 or less. | Page 40 |
| 3. A decimal point has not been displayed. | "0" is set in the parameter of $P - dP$. | Set the parameter of $\vec{P} - d\vec{P}$ to "1" or "2". | Page 42 |
| 4. The SV or the set values of some parameters have been changed without any operation. | ① The parameter of P-5L , P-5U , or P-dP was changed. | Set all the parameters again. (When the set values of the parameters of $P - 5L$, $P - 5U$, and $P - dP$ are changed, the set value of each parameter for which "*" is marked with the page 5 to 8 of the Parameter list, are changed.) | |
| | ② When the set value of $P - 5U$ is larger than 1000, "1" is registered for $P - dP$. | Set P-dP to "0", and return P-5! to an original value. | Page 40 |
| 5. ON/OFF control (Two-position control) has not started. | 0.0 is not set in the parameter of \boldsymbol{p} . | Set the parameter of P to 0.0. | Page 24 |
| 6. ON/OFF control has not function properly. | 1) The set value of parameter #45 is not correct. | Adjust the set value of parameter #45 to be suitable for the device to be controlled. | Page 27 |
| | ② The setting of parameter anaF is not correct. | Set the parameter $g \cap g F$ correctly. | Page 36 |
| 7. The Micro-controller is not controlling prop- | ① The set values of the parameters P , \vec{L} , and \vec{d} are not correct. | Perform the auto-tuning. | Page 20 |
| erly. | ② The cycle times are too long. | Decrease the set value of the parameters \(\int_{\infty} \) and \(\int_{\infty} \) gradually. | Page 37 |
| | ③ Output is limited. | Set the parameters of PL[1, PH[1, PL[2, and PH[2] again to be suitable for the process. | Page 62 |
| | (4) Output is not limited correctly. | Set the parameters of P[III] again to be suitable for the process. | Page 63 |

| Symptoms | Possible causes | Remedies | Reference pages |
|---|--|---|--------------------|
| 8. Response is too slow. (The measured value changes slowly.) | Input filter constant is too large. | Decrease the set value of the parameter of $P - dF$. | Page 45 |
| 9. Output changes be- | ① Some input terminals are short-circuited. | Remove the short-circuited terminals. | - |
| tween ON and OFF, but | 2 The connecting cable for the device to be | Connect it properly. | - |
| the reading does not | controlled are not connected properly. | | |
| change. | 3 The device to be controlled has powered off. | Power it on. | - |
| | 4 The output signals of the Micro-control- | Prepare the Micro-controller to be suitable for the | - |
| | ler do not match the input signals of the | device to be controlled. Or select the device to be | |
| | device to be controlled. | controlled to be suitable for the Micro-controller. | |
| 10. The keys do not operate. | "1", "2", "4", or "5" is set in the parameter of | Set the parameter of LoL to "0" or "3". | Page 23 |
| The set value of the param- | Lo[. | | |
| eters cannot be changed. | | | |
| 11. The SV cannot be changed. | ① "1", or "4" is set in the parameter of $\boldsymbol{L} \boldsymbol{\alpha} \boldsymbol{\zeta}$. | Set the parameter of LaC to "0", "2", "3" or "5". | Page 23 |
| | 2 You have tried to set the value that is out- | Widen the range of $5\vec{u} - \vec{k}$ to $5\vec{u} - \vec{k}$. (How- | Page 54 |
| | side of the SV limitter (Parameters of | ever, it should be within the set range in the | _ |
| | 5ū-L to 5ū-H). | input range table.) | |
| | 3 You have tried to change the SV during ramp-soak | Set the parameter of P_{ra} to aFF . | Page 18 |
| | operation (r lin, HL d, or End is selected.) | 1 22 2 | |
| 2. The parameters you want | The concerned parameters are set to skip in | Change the set value of the concerned dSP. | Page 78 |
| to confirm or change are | the parameters of d5P 1 to dP 13. | Change the set value of the concerned ds1. | lage 70 |
| - | and parameters of gg, 7 to g, 7g. | | |
| not displayed. | (A.C | | D 40 |
| 13. Auto-tuning does not | ① After starting the auto-tuning operation, | Set the parameters again so that the difference | Page 40 |
| work properly. | the display has showed [[][[][]] or | of the set values of $P - 5L$ and $P - 5U$ is made | |
| | LLLL. | larger, and perform the auto-tuning again. | |
| | 2 You have changed the SV after starting | Set the desirable SV, and perform the auto- | - |
| | the auto-tuning operation. | tuning again. | |
| | ③ The response of the controlled device was | Use a controller whose control cycle is fast, | - |
| | too fast. | such as PYH. | |
| | 4 You have tried to perform the auto-tuning | Set the parameter of P_{r_0} to $_0FF$, and per- | Page 18 |
| | during ramp-soak operation. | form the auto-tuning again. | |
| | (5) Peripheral devices have problems. Or they are not connected properly. | Connect them properly. | Page 57 |
| | (6) Direct/reverse actions are not suitable for the operations of the device to be controlled. | Set the parameter of P-n 1 properly. | Page 53 |
| | ① The response of the controlled device was | Perform the tuning manually. (Set the param- | Page 24 |
| | too slow, and the auto-tuning did not fin- | eter of P to "0" to try the ON/OFF control in | |
| | ish in 9 hours. | a hurry.) | |
| 14. An excessive over- | | (1) Perform the auto-tuning with the param- | Page 20 |
| shoot has occurred dur- | - | eter of A being "2" (Low PV type). | |
| ing auto-tuning opera- | | (2) Perform the tuning manually. | Page 24 |
| tion. | - | (2) I critim the tuning manually. | 1 450 27 |
| 15. The self-tuning does not work properly. | See the section of the parameter of $[\Gamma, \Gamma]$. | | Page 31 |
| 16. The PV display disappeared. | The set value of parameter dP 13 is not proper. | See the page of parameter dP 13. | Page 78 |

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△Safety Precaution

- Before using the PXR, read the "Instruction Manual" or consult with your local distributor or Fuji Electric for safety purpose.
- The uses and places for some of equipment described in this manual are limited. Some devices need regular inspections. Consult with your local distributor or Fuji Electric.
- Only electricians should connect this equipment.
- The contents of this manual have been prepared carefully. However, it should be noted that Fuji Electric is not responsible for any loss, including consequential damage from errors in writing or missing information.
 Before operating the PXR, carefully read the safety precaution in the "Instruction Manual".

Over-temperature Protection

Any control system design should take into account that any part of the system has the potential to fail.

For temperature control systems, continued heating should be considered the most dangerous condition, and the machine should be designed to automatically stop heating if unregulated due to the failure of the control unit or for any other reason.

The following are the most likely causes of unwanted continued heating:

- 1) Controller failure with heating output constantly on
- 2) Disengagement of the temperature sensor from the system
- 3) A short circuit in the thermocouple wiring
- 4) A valve or switch contact point outside the system is locked to keep the heat switched on.

In any application where physical injury or destruction of equipment might occur, we recommend the installation of independent safety equipment, with a separate temperature sensor, to disable the heating circuit in case of overheating.

The controller alarm signal is not designed to function as a protective measure in case of controller failure.

[Note] Modbus™ is a trademark of Modicon.
Ciltect ™ is a trade mark of CI Technology.

Consult on the PXR with the following:

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